Fundamental problem in concurrent programming:

Ensure co-ordinated access to shared resources

Ensure that a process is not interrupted by its peers during a critical section. Examples:

Avoid data races (two processes reading and incrementing a value)

Logical reasons (e.g., device can only execute one job at a time)

Time-critical operations (communication with hardware)

Complex transactions (multiple changes must be made at once to maintain consistency)

Abstract model:

A collection of processes, each with a critical section that is accessed from time to time.

Requirement: No more than one process may be in a critical section at any given moment.

Variant: No more than *k* processes may enter a critical section.

Processes are distinguished by some identifier.

Mutual exclusion happens in different environments:

inter-thread/process communication

single-core vs multi-core

processes running on different computers

Many algorithms and mechanisms and mechanisms exists to deal with different assumptions:

Interleaved vs true concurrency

Which actions are atomic (uninterruptible)?

Means of communication: synchronous, asynchronous, bounded delay

Some means of implementing mutual exclusion on a single machine:

Shared memory (synchronous). Problem: atomicity, data races

Inside the CPU: interrupt masks (but only kernel may use it)

Software solutions: Semaphores (or: Flags/Monitors/Locks)

A semaphore is a data structure with the following atomic operations:

lnit(n), where n = number of allowable concurrent accesses; inits counter to n

Wait: if counter positive, decrease it and return; otherwise wait until it becomes positive

Post: increase the counter

Typical use case for critical sections with semaphore:

```
Init(1);
while (1) {
    while (1) {
        ...;
        Wait();
        Critical1();
        Signal();
        ...;
        }
    }
}
```

Every access to a critical section is surrounded by Wait and Post.

Semaphore support at the OS level, see sem_overview(7):

SystemV semaphores: semget etc, older interface, no longer recommended

Posix locks (demo)

Unnamed semaphores (between related threads/processes): sem_init, sem_wait, sem_post

Named semaphores (system-wide): sem_open, sem_unlink

Naïve:

```
Init(n) { ctr = n; }
Wait() { while (ctr == 0); ctr = ctr-1; }
Signal() { ctr = ctr+1; }
```

Two problems:

Atomicity: no interruption must occur between reading and updating the value of $\mbox{ctr!}$

Waiting: active waiting or block/wakeup?

For POSIX semaphores, atomicity is ensured by blocking interrupts during Wait and Post (not available to normal user code!).

Passive waiting: block process until counter reaches non-zero state

requires OS-level support (for re-activating the process)

liberates CPU for other tasks (including doing nothing and saving energy)

but: necessitates at least two (costly) context switches

solution of choice for long waits, or on single-core CPU

So-called spinlocks use active waiting: periodically (or continuously) query counter state

burns CPU time; blocks other processes from executing

effective in true concurrency setting (e.g. multi-core CPU) if wait is guaranteed to be (very) short.

See also: pthread_spin_lock

Two processes, a producer (left) and a consumer (right).

The consumer uses up what the producer creates (data, requests, ...).

put and get are used to insert objects into a shared buffer of size N.

Init: counter = 0;

```
while (1) {
    produce(&object);
    while (counter == N);
    put(object);
    counter = counter+1;
    }
}
while (1) {
    while (1) {
    while (counter == 0);
    counter = counter-1;
    get(&object);
    consume(object);
    }
}
```

Note that this solution also requires atomic increment/decrement on counter.

```
Init(empty,N); Init(full,0);
```

```
while (1) {
    produce(&object);
    Wait(full);
    Wait(empty);
    put(object);
    Signal(full);
    Signal(full);
    }
}
```

Two sempaphores necessary to deal with both ends of the range 0..N.