

Logiques et modèles pour la vérification de systèmes infinis

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Soutenance de thèse de doctorat

10 novembre 2009

Cachan, France

Logics and Models for Verifying Infinite-state Systems

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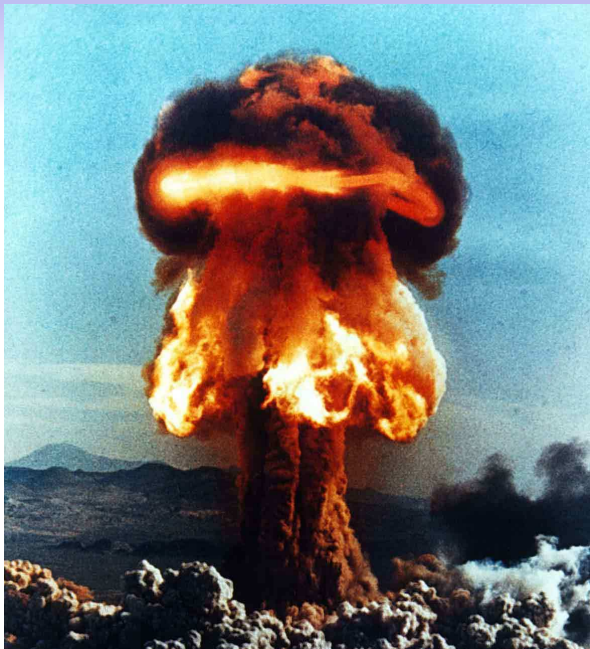
PhD defense
November 10th, 2009
Cachan, France

Context



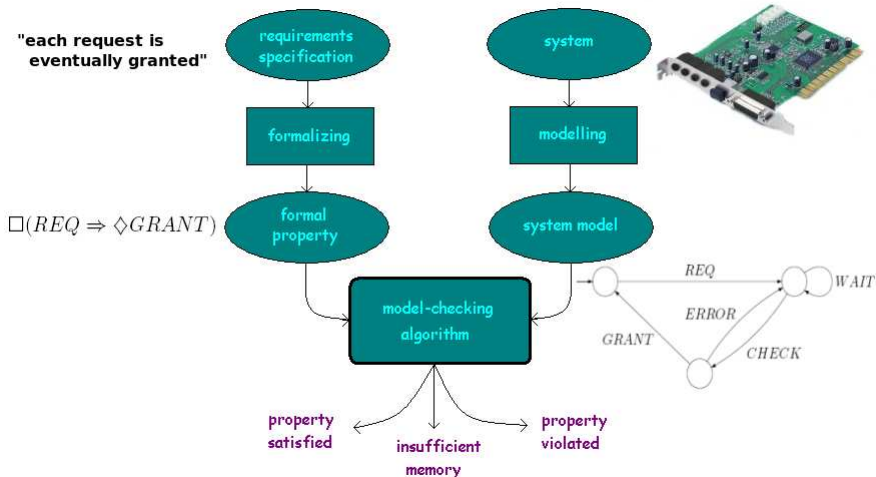
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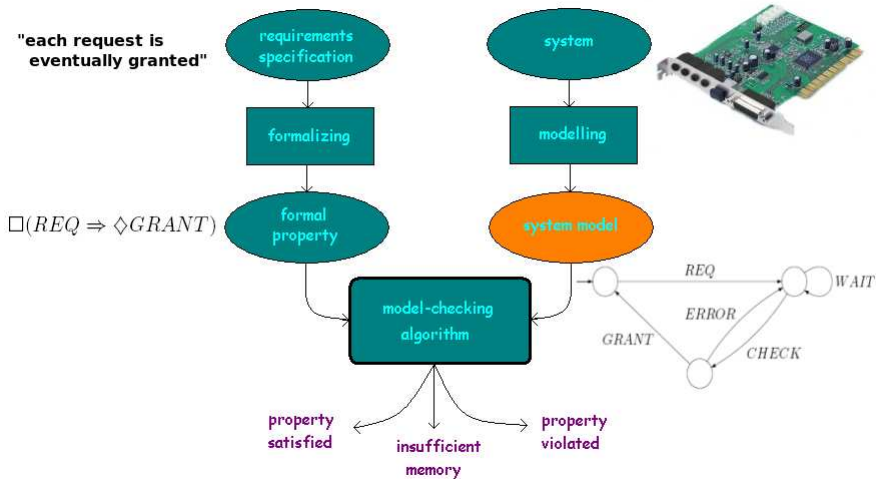
Model Checking

“Does a system achieve exactly what we want it to?”



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Modelling Systems with Automata

Capturing the behaviour of a system

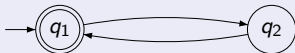
- Control state of the automaton = general “state” of the system
(e.g. *idle, printing, moving, waiting, etc.*)
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Example: an automaton

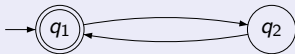


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Need for richer models, closer to reality

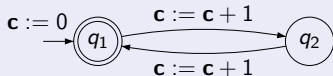
Extend automata with:
stacks, FIFO channels, **integer or real variables**, trees, etc.

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Example: an automaton with one counter



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Representing Sets with Arithmetical Logics

Extending automata with variables...

...generates an infinite set of configurations!

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Definition

Two logics L, L' (resp. formulas F, F') are equivalent iff they define the same sets. We denote it by $L \equiv L'$ (resp. $F \equiv F'$).

Outline

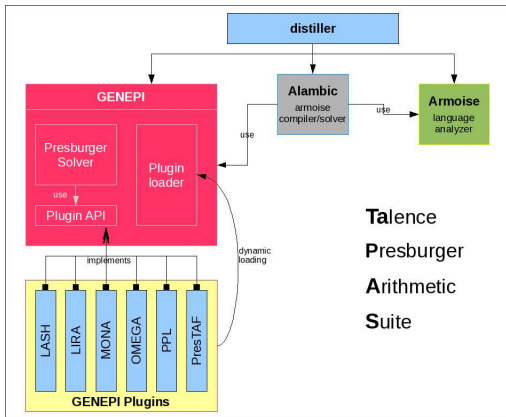
- 1 Decomposing Mixed/Real Logics**
 - Principle of the Decomposition
 - Application over MLA and Extended MLA
- 2 Timed Counter Systems**
 - Definitions
 - Region Graph
 - Decidable Subclasses
- 3 Dense-choice Counter Machines**
 - Definitions
 - Logical Characterization

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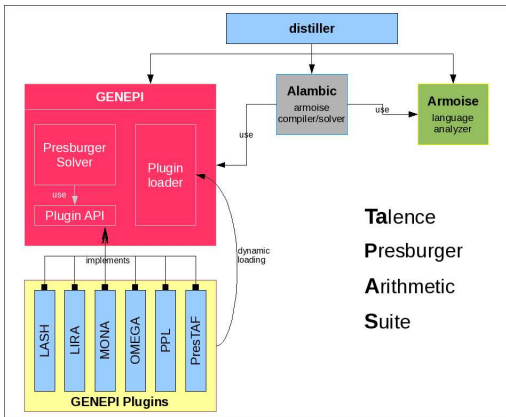
Motivation

Represent vectors of real values by using the modular framework of the GENEPI tool [*Leroux & Point, 06*]:



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Extract the integer component from reals, to use periodicity

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Finite Unions of Sums “Integer+Decimal”

For any $A, B \subseteq \mathbb{R}$, let $A + B = \{a + b \mid a \in A, b \in B\}$.

Example: a real formula decomposed as “ $\cup(int + dec)$ ” ...

$$\begin{aligned} & \left(\{(x, y) \mid 0 \leq x < 10^6 \wedge y = 0\} + \{(x, y) \in [0, 1]^2 \mid x = y\} \right) \\ & \cup \left(\{(x, y) \mid x = 10^6 \wedge y = 0\} + \{(x, y) \in [0, 1]^2 \mid x \geq y\} \right) \\ & \cup \left(\{(x, y) \mid x > 10^6 \wedge y = 0\} + \{(x, y) \in [0, 1]^2\} \right) \end{aligned}$$

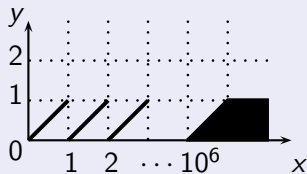
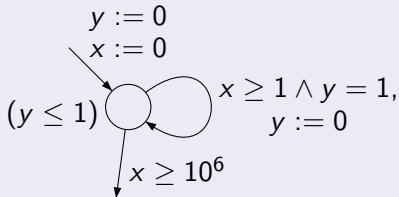
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...representing the clock values of a timed automaton:



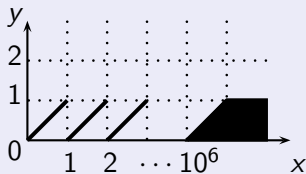
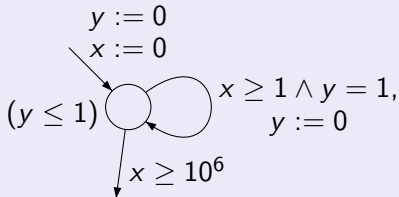
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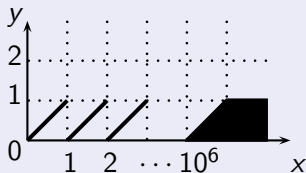
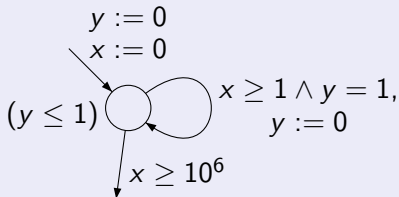
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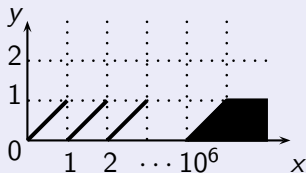
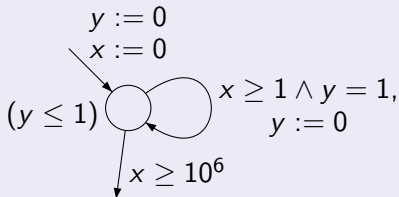
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Our representation

- Let $\mathfrak{Z} \subseteq P(\mathbb{Z}^n)$ and $\mathfrak{D} \subseteq P(\mathbb{D}^n)$, where $\mathbb{D} = [0, 1[$

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$$\text{Counter-example: } R = \bigcup_{j=1}^{\infty} \left(\{j\} + \left\{ \frac{1}{j+1} \right\} \right)$$

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A class $\mathfrak{R} \subseteq \bigcup_{n \in \mathbb{N}} P(\mathbb{R}^n)$ is *effectively representable* if it is stable and if there exist algorithms computing the above operations.

Our representation (continued)

Theorem (\oplus -Decidability)

The SATisfiability problem is decidable for any logic encoding $\exists \oplus \mathcal{Q}$ if \exists and \mathcal{Q} are effectively representable.

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Proof sketch

- $(Z_1 + D_1) \cap (Z_2 + D_2) = (Z_1 \cap Z_2) + (D_1 \cap D_2)$
- $(Z_1 + D_1) \setminus (Z_2 + D_2) = ((Z_1 \setminus Z_2) + D_1) \cup (Z_1 + (D_1 \setminus D_2))$
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- similarly, projection and permutation distribute easily over \uplus
- \mathbb{R}^n can be written $\mathbb{Z}^n + \mathbb{D}^n$
- $R_+ = \{\mathbf{r} \in \mathbb{R}^3 \mid r_1 + r_2 = r_3\}$ can be written

$$\bigcup_{c \in \{0,1\}} \{\mathbf{z} \in \mathbb{Z}^3 \mid z_1 + z_2 + c = z_3\} + \{\mathbf{d} \in \mathbb{D}^3 \mid d_1 + d_2 = d_3 + c\}$$
- similarly, $\emptyset, \leq, \mathbb{Z}^n$ are easily definable □

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A quick reminder about logics...

Presburger logic: $\text{FO}(\mathbb{Z}, +, \leq)$

expression $E ::= 0 \mid 1 \mid x \mid E + E \mid E - E$

atomic formula $C ::= E = E \mid E < E$

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Example: a **non**-Presburger-definable set

There is no Presburger formula defining the set $\{2^n \mid n \in \mathbb{N}\}$.

A quick reminder about logics... (continued)

Mixed Linear Arithmetic (MLA): $\text{FO}(\mathbb{R}, \mathbb{Z}, +, \leq)$

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Decomposing MLA and Extended MLA

Theorem [TIME'08]

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Proof idea

- Application of the \uplus -Decidability theorem
- Mutual encodings of X_b, V_b, W_b

Extended MLA: X_b, V_b, W_b

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Example illustrating X_b, V_b, W_b

$$x = (42.0625)_{10} = (0^*101010 \star 00010^\omega)_2$$

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 X_2(x, 2^1, 1) \\
 \downarrow \\
 X_2(x, 2^4, 0) \quad X_2(x, 2^{-2}, 0) \\
 \swarrow \quad \downarrow \quad \nwarrow \\
 x = (42.0625)_{10} = (0^*101010^*00010^\omega)_2 \\
 \uparrow \\
 V_2(x) = 2^1
 \end{array}$$

Extended MLA: X_b, V_b, W_b

Proposition [TIME'08]

$$\text{FO}(\mathbb{R}, \mathbb{Z}, +, \leq, X_b) \equiv \text{FO}(\mathbb{Z}, +, \leq, V_b) \uplus \text{FO}(\mathbb{D}, +, \leq, W_b)$$

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Proof idea: mutual encodings of X_b, V_b, W_b

$$\begin{aligned} X_b(x, u, a) \equiv & \exists w \in \mathbb{D}, \exists y \in \mathbb{Z}, \exists z \in \mathbb{R}, \\ & x = w + y + z + au \wedge z < u \\ & \wedge \left((u \geq 1 \wedge V_b(y) \geq bu) \vee (u < 1 \wedge W_b(w) \geq bu) \right) \end{aligned}$$

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Motivation

Initial observation

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and we study their reachability matters*

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Definitions

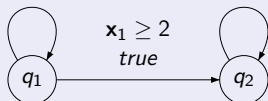
Example: a Timed Counter System (TCS)

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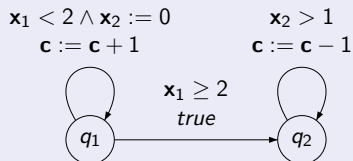
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Definitions

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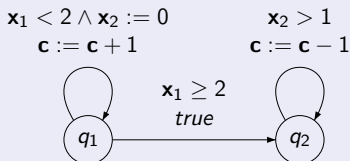
X = a set of m real-valued variables, called **clocks**.

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C = a set of n integer-valued variables, called **counters**.

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R_C = Presburger-definable binary relations over counters

Definitions (continued)

Definition [INFINITY'08]

A **Timed Counter System** is a tuple $\langle Q, X, C, E \rangle$ where:

- Q is a finite set of control states
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Definition

A *Timed Automaton* is a TCS where $C = \emptyset$.

A *Counter System* is a TCS where $X = \emptyset$.

Semantics of a TCS

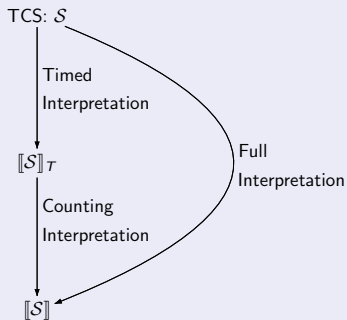
For any TCS \mathcal{S} , define its:

- Counting Transition System $\llbracket \mathcal{S} \rrbracket_C$
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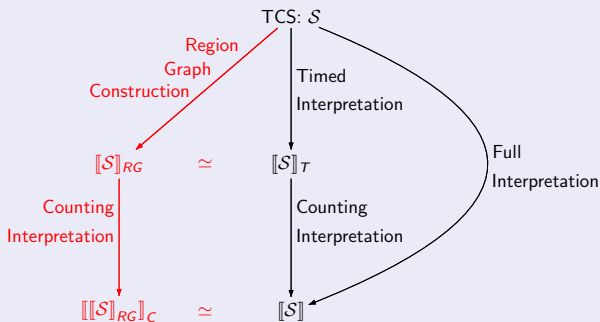
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Semantics of a TCS

For any TCS \mathcal{S} , define its:

- Counting Transition System $[[\mathcal{S}]]_C$
- Timed Transition System $[[\mathcal{S}]]_T$ \simeq Region Graph $[[\mathcal{S}]]_{RG}$
- (full) Transition System $[[\mathcal{S}]]$ $\simeq [[[\mathcal{S}]]_{RG}]_C$



Reachability

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Counter Reachability Problem (CRP)

Inputs: A TCS \mathcal{S} , an initial configuration $(q_0, \mathbf{x}_0, \mathbf{c}_0)$ of $\llbracket \mathcal{S} \rrbracket$, and a configuration (q, \mathbf{c}) of $\llbracket \mathcal{S} \rrbracket_{\mathbf{c}}$.

Question: Is there a clock valuation \mathbf{x} such that $(q, \mathbf{x}, \mathbf{c})$ is reachable from $(q_0, \mathbf{x}_0, \mathbf{c}_0)$ in $\llbracket \mathcal{S} \rrbracket$?

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CRP extends reachability problem of CS, known to be undecidable [*Minsky, 61*]; therefore **CRP is undecidable for TCS**.

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Counter+region Reachability Problem (CRP)

Inputs: A TCS \mathcal{S} , an initial configuration $(q_0, \rho_0, \mathbf{c}_0)$ of $\llbracket \mathcal{S} \rrbracket$, a region ρ , and a configuration (q, \mathbf{c}) of $\llbracket \mathcal{S} \rrbracket_{\mathbf{C}}$.

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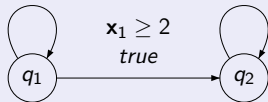
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Regions

Timed Counter System \mathcal{S}

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Regions

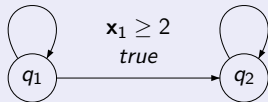
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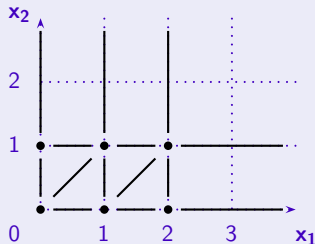
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Clock regions of \mathcal{S}



28 regions in total:

6 points, 9 line segments, 5 half-lines, 4 triangular closed areas, and 4 open areas

Regions

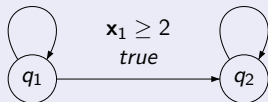
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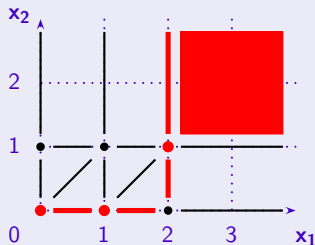
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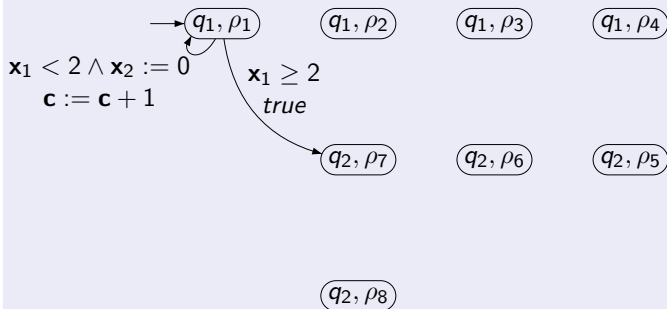
Reachable clock regions of \mathcal{S}



8 **reachable** regions (out of 28), considering the initial configuration $(q_1, \binom{0}{0}, 0)$

Region Graph

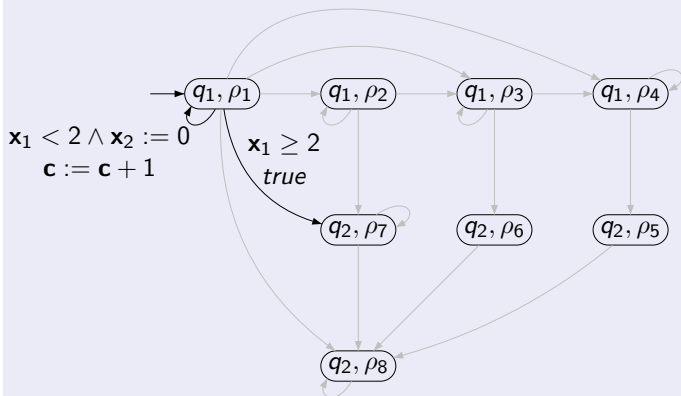
Region Graph $[[S]]_{RG}$



N.B.: ρ_i are the 8 reachable regions

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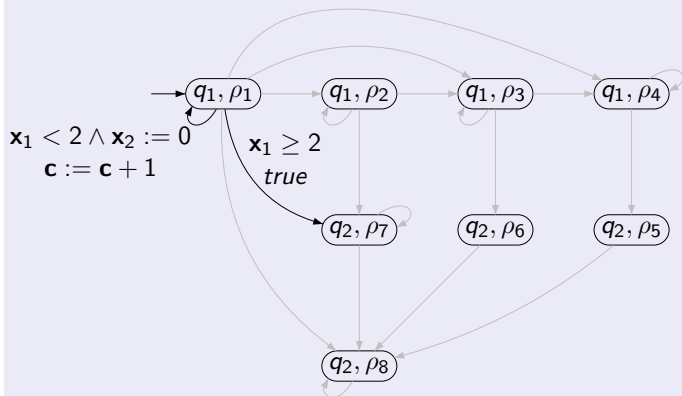
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Region Graph

Region Graph $\llbracket S \rrbracket_{RG}$ is a Counter System!



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The Region Graph as a Counter System

Key idea of the analysis of TCS:

For a TCS \mathcal{S} , its region graph $[[\mathcal{S}]]_{RG}$ is also a Counter System.

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Let \mathcal{C} be a class of TCS such that there is an algorithm solving the reachability problem for $\llbracket \mathcal{S} \rrbracket_{RG}$, for any $\mathcal{S} \in \mathcal{C}$.

(e.g. \mathcal{C} can be VASS/Petri Nets, bounded CS, etc.)

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The Counter Reachability Problem is decidable for \mathcal{C} .

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Proof sketch ▶ time-abstract bisimulation

- By definition, $\llbracket \llbracket \mathcal{S} \rrbracket_T \rrbracket_C = \llbracket \llbracket \mathcal{S} \rrbracket_C \rrbracket_T = \llbracket \mathcal{S} \rrbracket$.
- $\llbracket \mathcal{S} \rrbracket_{RG} \simeq \llbracket \mathcal{S} \rrbracket_T$ [Alur & Dill, 90].
- Therefore $\llbracket \llbracket \mathcal{S} \rrbracket_{RG} \rrbracket_C \simeq \llbracket \mathcal{S} \rrbracket$. □

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Subclasses of TCS

Decidability results

Model	Region Graph	Counter Reach. Prob.
TCS	CS	Undecidable
TVASS	VASS	Decidable
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- **Timed Counter Machine** (TCM) = TCS whose relations on counters are translations with guards of the form $\mathbf{c} \geq k$ or $\mathbf{c} = k$, with $k \in \mathbb{N}^n$
- **Timed VASS** (TVASS) = TCM with only $\mathbf{c} \geq k$ guards
- **Bounded TCS** = TCS whose counter values are bounded
- **Reversal-Bounded TCM** = TCM whose counters do a bounded number of alternations between increasing and decreasing modes

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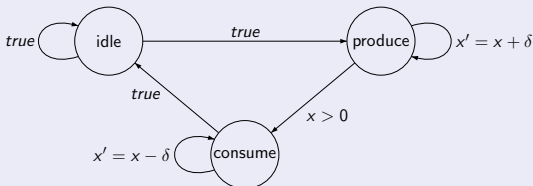
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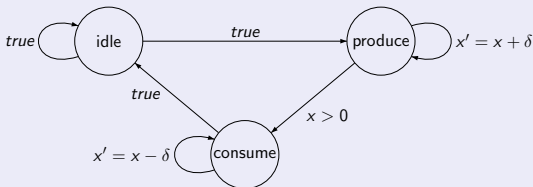
Example: a Dense-choice Counter Machine (DCM)



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A new value δ is chosen in $]0, 1[$ at each step!

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Guards $G = \{(x = 0), (x > 0), \text{true}\}$

Actions $A = \{1, \Delta\}$ (i.e. increments/decrements)

☞ 1 is “integer”, Δ is “non-deterministically-chosen decimal”

DCM

A **Dense-choice Counter Machine** with $n > 0$ counters is a tuple $\mathcal{M} = \langle S, T \rangle$ where:

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Example

A transition $x > 0 \wedge x := x - 3\delta$ is written $(x = 0, -3, \Delta)$.

Definitions (continued)

Semantics of a DCM $\mathcal{M} = \langle S, T \rangle$

The transition system $TS(\mathcal{M}) = \langle C, \rightarrow \rangle$ is defined by:

- $C = S \times \mathbb{R}_+^n$ is the set of configurations
- $\rightarrow \subseteq C \times \Sigma \times C$ is the set of transitions, defined by:

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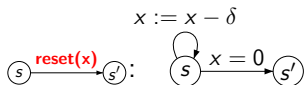
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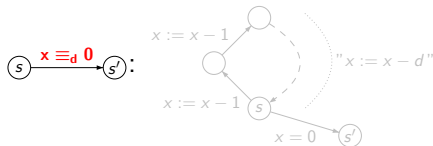
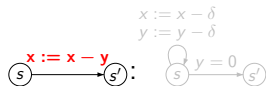
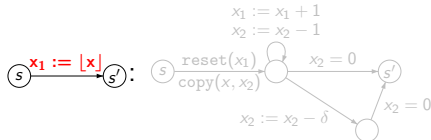
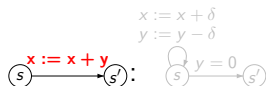
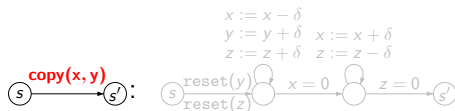
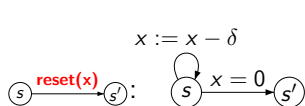
Subclasses of DCM

- **purely-DCM**: $a_i = \Delta$ for each counter $i \leq n$
- **(discrete) CM**: $a_i = 1$ for each counter $i \leq n$ (i.e. Minsky machine)
- **reversal-bounded DCM**: $\exists r \in \mathbb{N}$ s.t. on every run, each counter switches between increments and decrements at most r times
- **bounded DCM**: $\exists b \in \mathbb{N}$ s.t. on every run, no counter exceeds b

Encodings of macro-operations in DCM



Encodings of macro-operations in DCM



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Reversal-Bounded DCM and MLA

Theorem [Ibarra, 78]

The reachability relation of a reversal-bounded CM is definable in Presburger logic.

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Theorem [*INFINITY'09*]

Each MLA formula defines the reachability relation of a reversal-bounded DCM.

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- Decidability proofs for SATisfiability of logics

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- Full logical characterization of reversal-bounded DCM with MLA

Future Work

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- Study new logics through decomposition (for charac. & decidability)
- Extend decidable subclasses (flat TCS)
- Generalize TCS analysis technique to Timed *Heterogeneous* Systems
- Solve open decidability problems for subclasses of DCM
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Implementation

- Enhance GENEPI prototype decomposing logics
- Implement region construction in FAST
- Design a tool for reversal-bounded DCM