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# A PROBABILISTIC AND NON-DETERMINISTIC CALL-BY-PUSH-VALUE LANGUAGE

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PARIS-SACLAY



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- PCF, probabilistic choice, and the trouble with  $\mathbf{V}$
  - Curing the trouble using call-by-push-value
  - Semantics, adequacy, full abstraction
-

# PLOTKIN'S PCF (1977)

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## LCF CONSIDERED AS A PROGRAMMING LANGUAGE

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Robin Milner

This paper studies connections between denotational and operational semantics for a programming language based on LCF. It begins with the connection between the operational semantics and its denotation. It turns out that a program denotes  $\perp$  in any of several denotational semantics if and only if it does not terminate. From this it follows that if two terms have the same denotation in all these semantics, they have the same behaviour in all contexts. The converse is also true. If, however, the language is extended to allow certain parallel facilities, the operational semantics does not coincide with denotational equivalence in one of the semantics. A semantics may therefore be called “fully abstract”. Next a connection is given which characterises the operational semantics up to isomorphism from the behaviour alone. Conversely, by allowing further parallel facilities, every r.e. element of the fully abstract semantics becomes operationally definable, thus characterising the programming language, up to interdefinability, from the set of r.e. elements of the domains of the semantics.

### 1. Introduction

We present here a study of some connections between the operational and denotational semantics of a simple programming language based on LCF [3, 5]. While this language is itself rather far from the commonly used languages, we do hope that the kind of connections studied will be illuminating in the study of these languages too.

The first connection is the relation between the behaviour of a program and the

- Types  $\sigma, \tau, \dots ::= \mathbf{int} \mid \sigma \rightarrow \tau$
- Terms  $M, N, \dots ::= x_\tau$ 
  - |  $MN$
  - |  $\lambda x_\sigma. M$
  - |  $\mathbf{rec} x_\sigma. M$
  - |  $\underline{n}$
  - |  $\mathbf{succ} M$
  - |  $\mathbf{pred} M$
  - |  $\mathbf{ifz} M N P$
- (All terms are typed. Call by name.)

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# PLOTKIN'S PCF (1977)

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■ (All terms are typed. Call by name.)

■ An **operational** semantics:

$M \rightarrow^* N$

■ A **denotational** semantics:

$\llbracket M \rrbracket$

■ **Adequacy:**

for every ground  $M : \mathbf{int}$ ,

$\llbracket M \rrbracket = n$  iff  $M \rightarrow^* \underline{n}$

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for every ground  $M : \mathbf{int}$ ,

$$\llbracket M \rrbracket = n \text{ iff } M \rightarrow^* \underline{n}$$

- **Contextual preordering:**

$$M \leq N \text{ iff}$$

for every context  $C : \mathbf{int}$ ,

$$C[M] \rightarrow^* \underline{n} \Rightarrow C[N] \rightarrow^* \underline{n}$$

- **Fact:** if  $\llbracket M \rrbracket \leq \llbracket N \rrbracket$  then  $M \leq N$

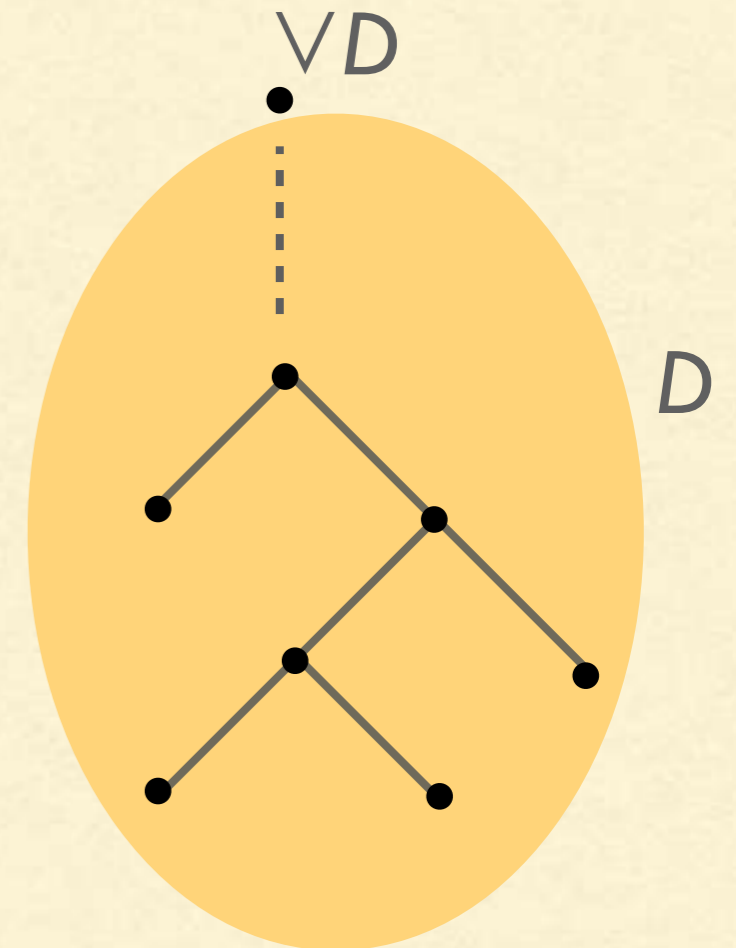
- Converse is **full abstraction**.  
Fails for PCF, works for PCF+**por**
-

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# DCPOS

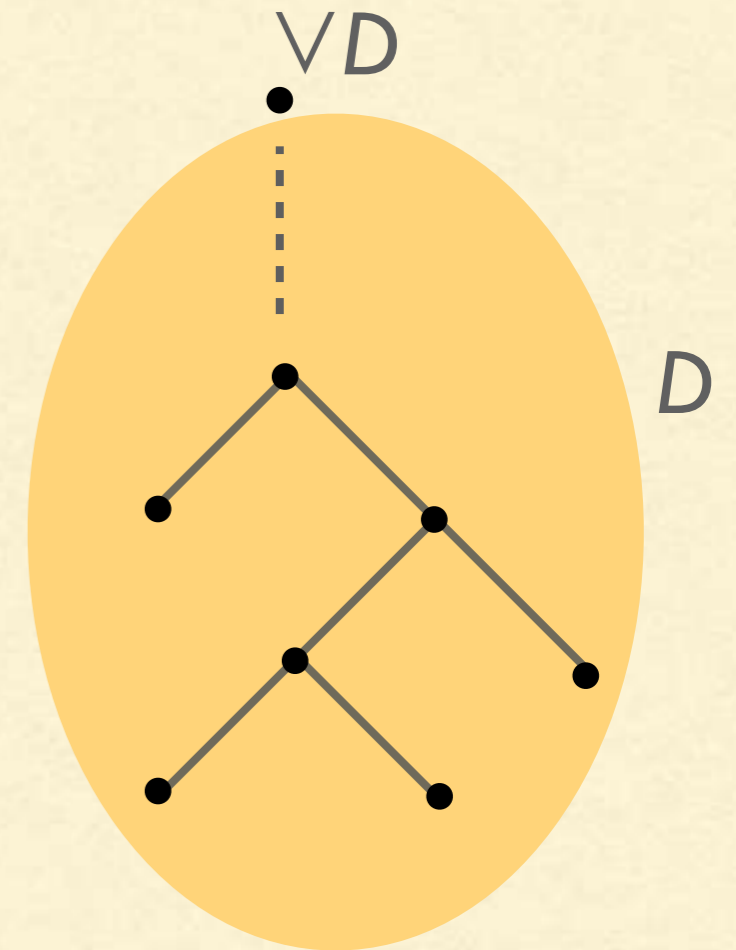
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- Every type  $\tau$  interpreted as a **dcpo**  $\llbracket \tau \rrbracket \dots$   
= poset in which every directed family  $D$   
has a supremum  $\bigvee D$



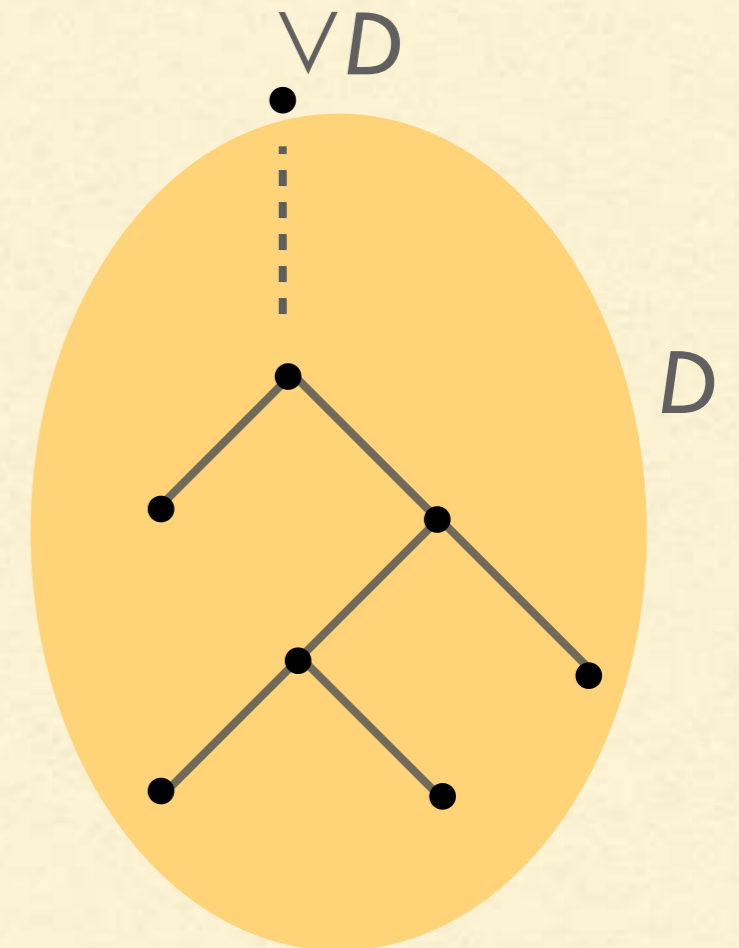
# DCPOS

- Every type  $\tau$  interpreted as a **dcpo**  $[[\tau]]$ ...  
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- $[[\mathbf{int}]] = \mathbb{Z}_{\perp}$  ( $\perp \leq n$ , all  $n$  incomparable)



# DCPOs

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- $\llbracket \mathbf{int} \rrbracket = \mathbb{Z}_\perp$  ( $\perp \leq n$ , all  $n$  incomparable)
- $\llbracket \sigma \rightarrow \tau \rrbracket = \llbracket \llbracket \sigma \rrbracket \rightarrow \llbracket \tau \rrbracket \rrbracket$ ,  
dcpo of Scott-continuous maps :  $\llbracket \llbracket \sigma \rrbracket \rightarrow \llbracket \tau \rrbracket \rrbracket$   
(monotonic + preserves directed sups)





# THE SEMANTICS OF PCF

■ Types  $\sigma, \tau, \dots ::= \mathbf{int} \mid \sigma \rightarrow \tau$

■ Terms  $M, N, \dots ::= x_\tau$   
|  $MN$   
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$\in [\sigma \rightarrow \tau]$

$\in [\sigma]$

■  $\llbracket MN \rrbracket = \llbracket M \rrbracket(\llbracket N \rrbracket)$

$\llbracket \lambda x_\sigma. M \rrbracket = (V \mapsto \llbracket M \rrbracket[x_\sigma := V])$

$\in [\sigma]$

$\in [\tau]$

■ Meaningful since **Dcpo** is a Cartesian-closed category

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# CARTESIAN-CLOSEDNESS

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- $\in [\sigma \rightarrow \tau]$   $\in [\sigma]$   
■  $\llbracket MN \rrbracket = \llbracket M \rrbracket(\llbracket N \rrbracket)$   
 $\llbracket \lambda x_\sigma . M \rrbracket = (V \mapsto \llbracket M \rrbracket[x_\sigma := V])$   
 $\in [\sigma]$   $\in [\tau]$
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- In order to prove full abstraction (with por), we require to be able to **approximate** elements of  $[\tau]$  by **definable** elements  $\llbracket M \rrbracket$ .
  - In the case of PCF, each  $[\tau]$  is an **algebraic bc-domain**, making that possible.
  - Cartesian-closed... good.
-

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# CCCS OF CONTINUOUS DCPOS

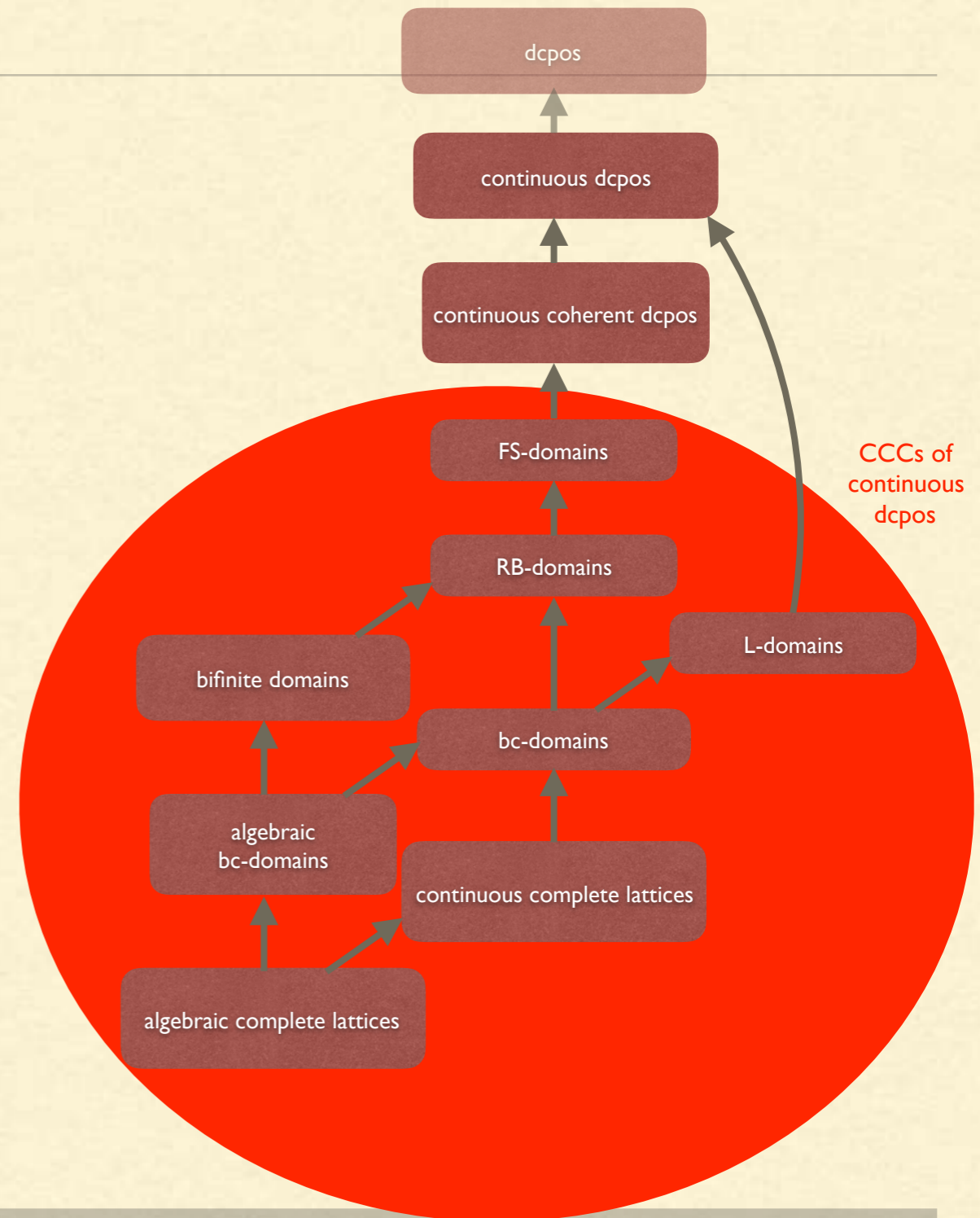
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algebraic  
bc-domains

# CCCS OF CONTINUOUS DCPOS

- In order to prove full abstraction (with por), we require to be able to **approximate** elements of  $\llbracket \tau \rrbracket$  by **definable** elements  $\llbracket M \rrbracket$ .
- In the case of PCF, each  $\llbracket \tau \rrbracket$  is an **algebraic bc-domain**, making that possible.
- Cartesian-closed... good.
- Many other CCCs would fit.



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# CONTINUOUS DCPOS

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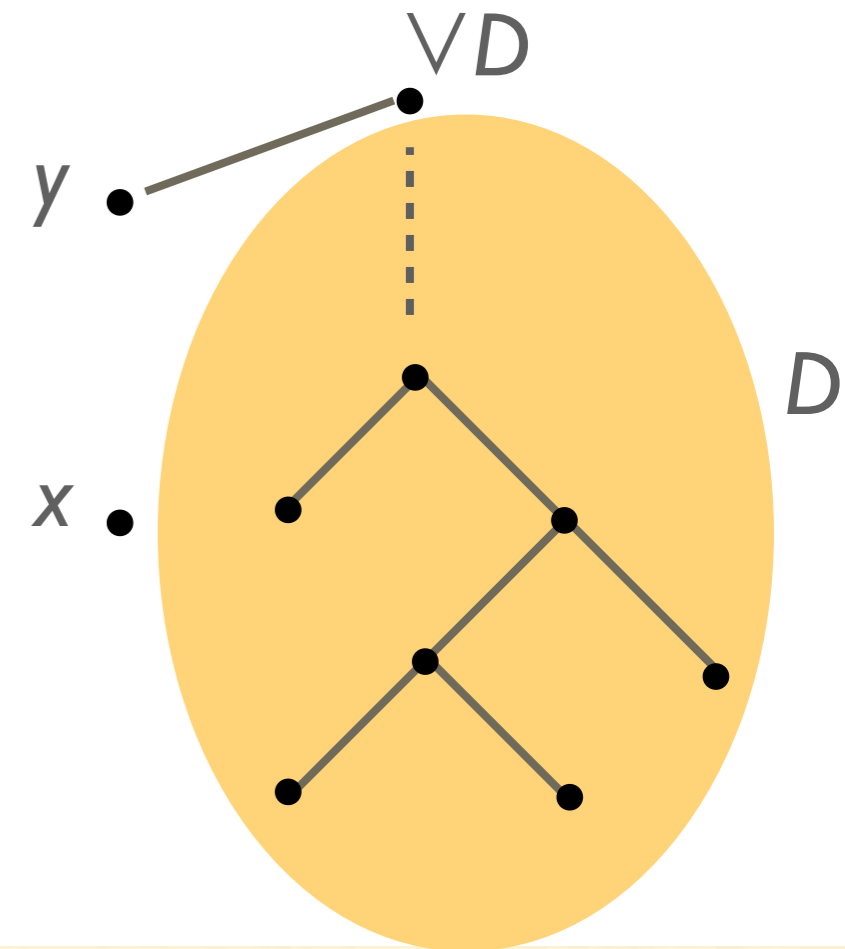
- **Approximation (way-below):**  
 $x \ll y$  iff for every directed  $D$  such that  $y \leq \bigvee D$ ,  
 $x$  is already below some element of  $D$

$y \bullet$

$x \bullet$

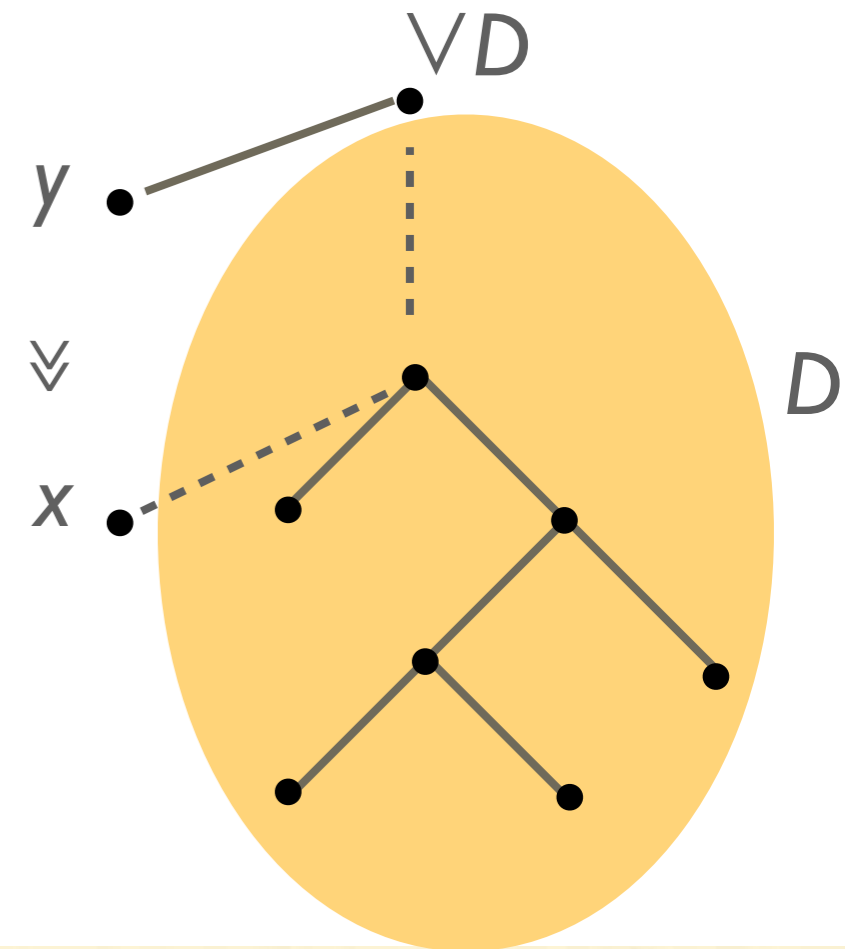
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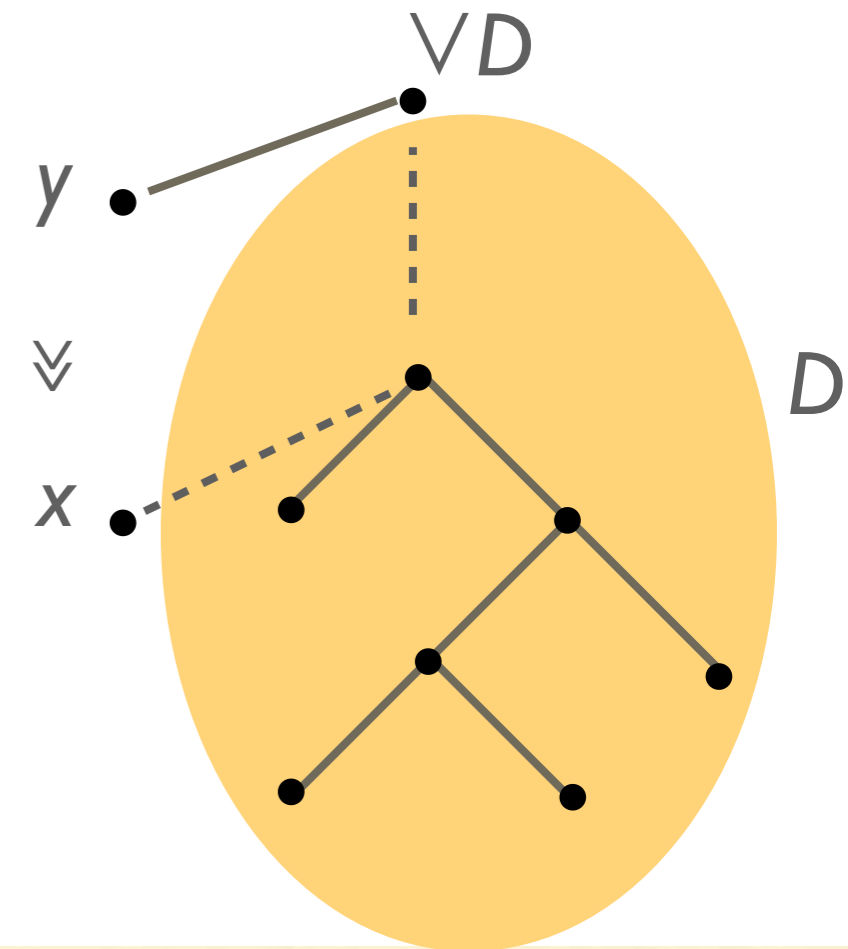
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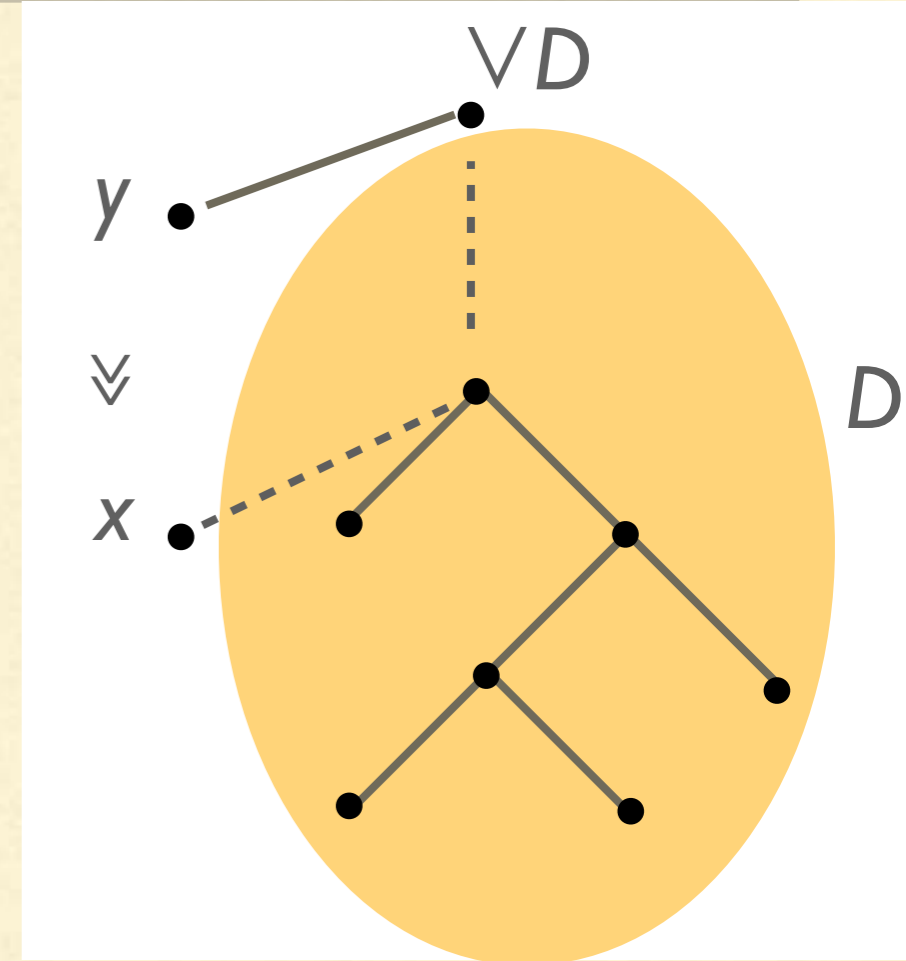
- **Approximation (way-below):**  
 $x \ll y$  iff for every directed  $D$  such that  $y \leq \bigvee D$ ,  
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- A **basis**  $B$  of a dcpo  $X$  iff for every  $x$ ,  
 $\{b \in B \mid b \ll x\}$  directed and has  $x$  as sup  
A dcpo  $X$  is **continuous** iff has a basis





# CONTINUOUS DCPOs

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A dcpo  $X$  is **continuous** iff has a basis
- Ex: the finite subsets of  $A$  form a basis of  $\mathbf{P}(A)$  with inclusion  
 $\mathbb{N}$  forms a basis of  $\mathbb{N} \cup \{\infty\}$   
 $\mathbb{Q}_+$  forms a basis of  $\mathbb{R}_+ \cup \{\infty\}$  ( $x \ll y$  iff  $x=0$  or  $x < y$  here)



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# ADDING PROBABILITIES

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- Types  
 $\sigma, \tau, \dots ::= \mathbf{int} \mid \sigma \rightarrow \tau \mid \mathbf{V}\tau$
  - Terms  $M, N, \dots ::= \dots$ 
    - |  $M \oplus N$
    - |  $\mathbf{ret} M$
    - |  $\mathbf{do} x_\sigma \leftarrow M; N$
-

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$\sigma, \tau, \dots ::= \mathbf{int} \mid \sigma \rightarrow \tau \mid \mathbf{V}\tau$

Monadic type of subprobability  
valuations over  $\tau$

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with  $M, N: \mathbf{V}\tau$ ,  
choose between  $M$  and  $N$   
with probability 1/2

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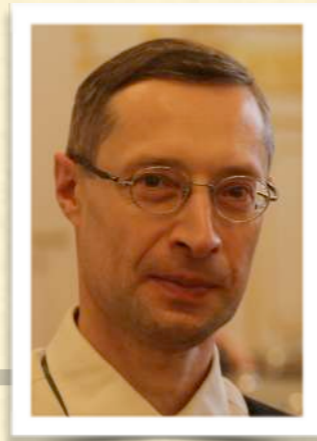
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monadic constructions:

$M:\tau \Rightarrow \mathbf{ret} M:\mathbf{V}\tau$

$M:\mathbf{V}\sigma \ N:\mathbf{V}\tau \Rightarrow \mathbf{do} x_\sigma \leftarrow M; N : \mathbf{V}\tau$



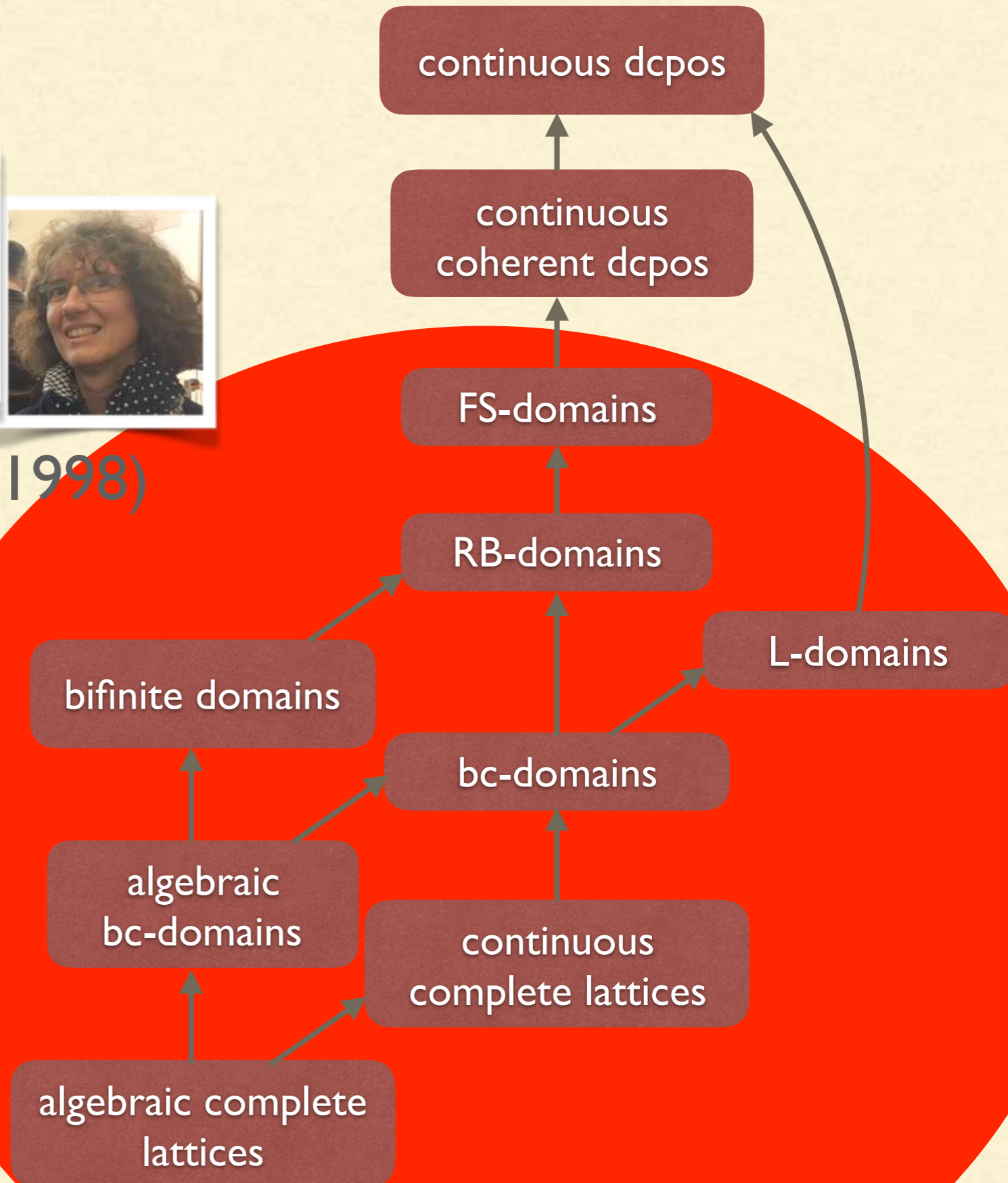
(Moggi 1991)

# THE TROUBLE WITH $\mathbf{V}$



(Jung, Tix 1998)

- Look for a category of continuous dcpos that is...

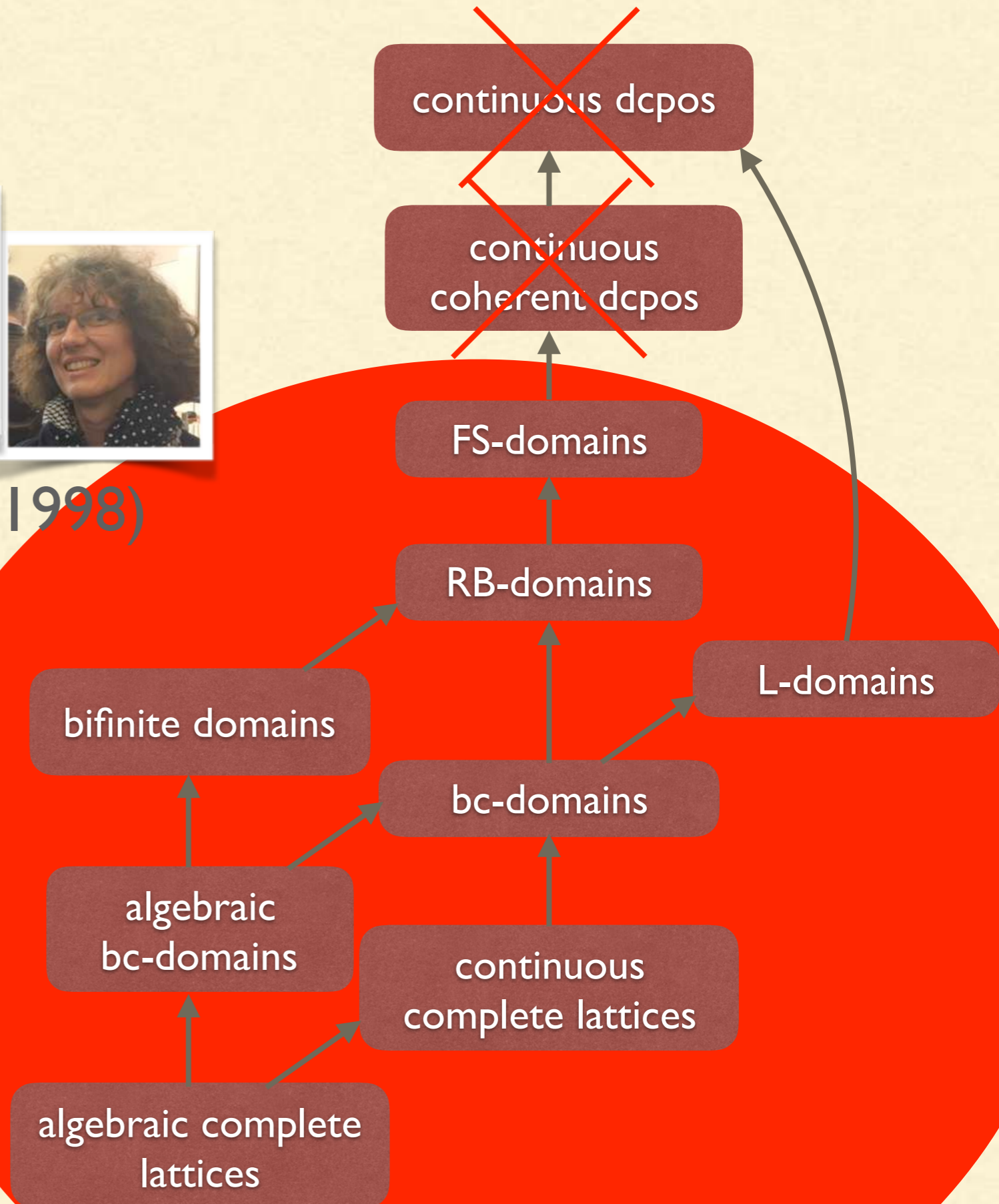


# THE TROUBLE WITH $\mathbf{V}$



(Jung, Tix 1998)

- Look for a category of continuous dcpos that is...
- **Cartesian-closed**

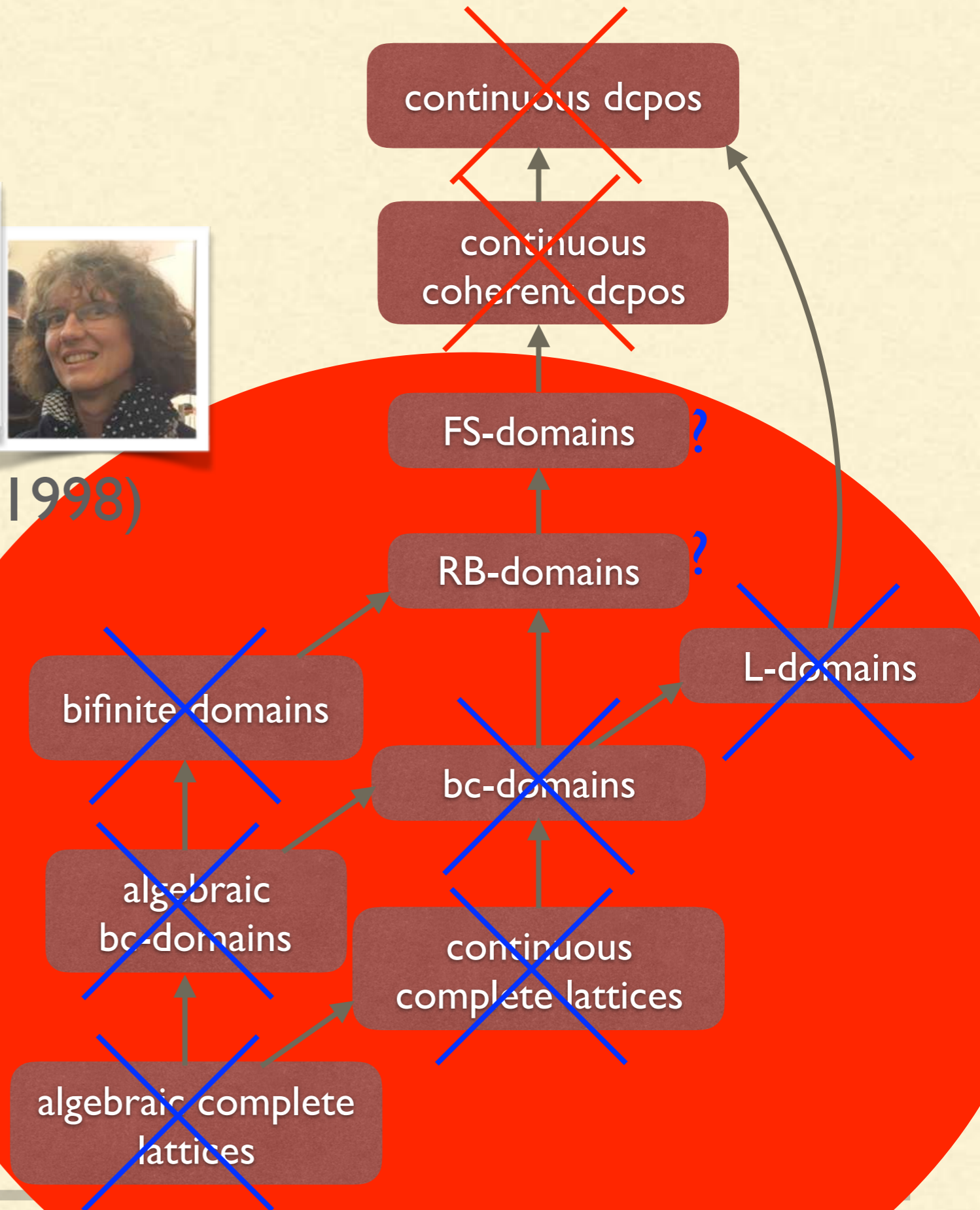


# THE TROUBLE WITH $\mathbf{V}$



(Jung, Tix 1998)

- Look for a category of continuous dcpos that is...
- Cartesian-closed
- closed under  $\mathbf{V}$



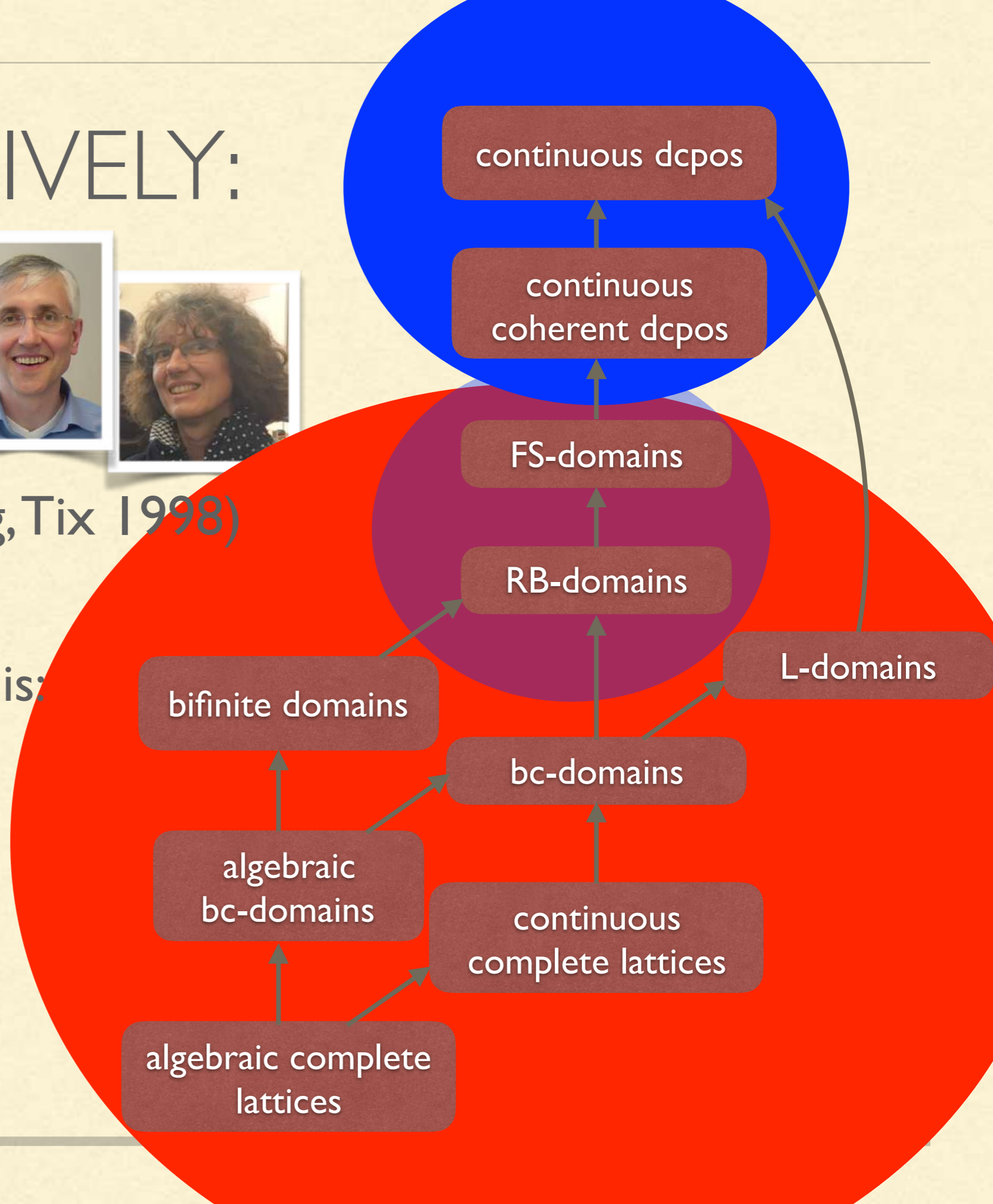


# MORE POSITIVELY:



(Jung, Tix 1998)

- Look for a category of continuous dcpos that is:
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- **closed under  $\mathbf{V}$**

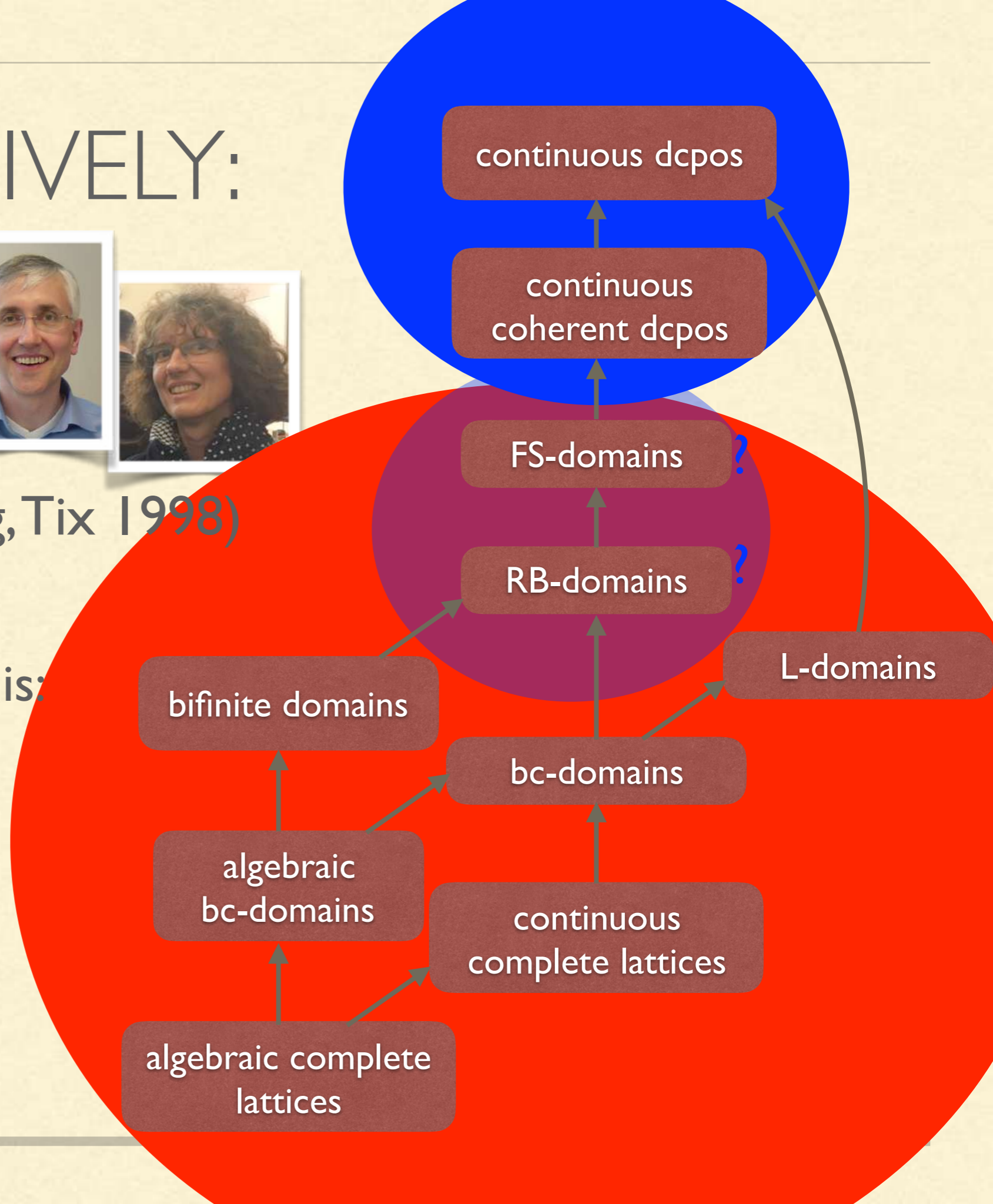


# MORE POSITIVELY:



(Jung, Tix 1998)

- Look for a category of continuous dcpos that is:
- Cartesian-closed
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# OTHER SOLUTIONS (I)

- Change categories entirely.  
E.g., reason in **probabilistic coherence spaces**
- Equationally **fully abstract** semantics  
(Ehrhard, Pagani, Tasson 14)
- also for call-by-push-value  
(Ehrhard, Tasson 19)
- probabilistic choice 'built-in'



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# OTHER SOLUTIONS (2)

---

- Change categories, and opt for **QCB spaces/predomains** (Battenfeld 06)
  - ... Cartesian-closed, and has a probabilistic choice monad



---

# OTHER SOLUTIONS (2)

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- Change categories, and opt for **QCB spaces/predomains** (Battenfeld 06)  
... Cartesian-closed, and has a probabilistic choice monad
- Changes categories, and opt for **quasi-Borel spaces/ domains**  
(Heunen, Kammar, Staton, Yang 17; Vákár, Kammar, Staton 19)  
... Cartesian-closed,  
and closed under a ‘laws of random variables’ functor



# BACK TO DOMAINS

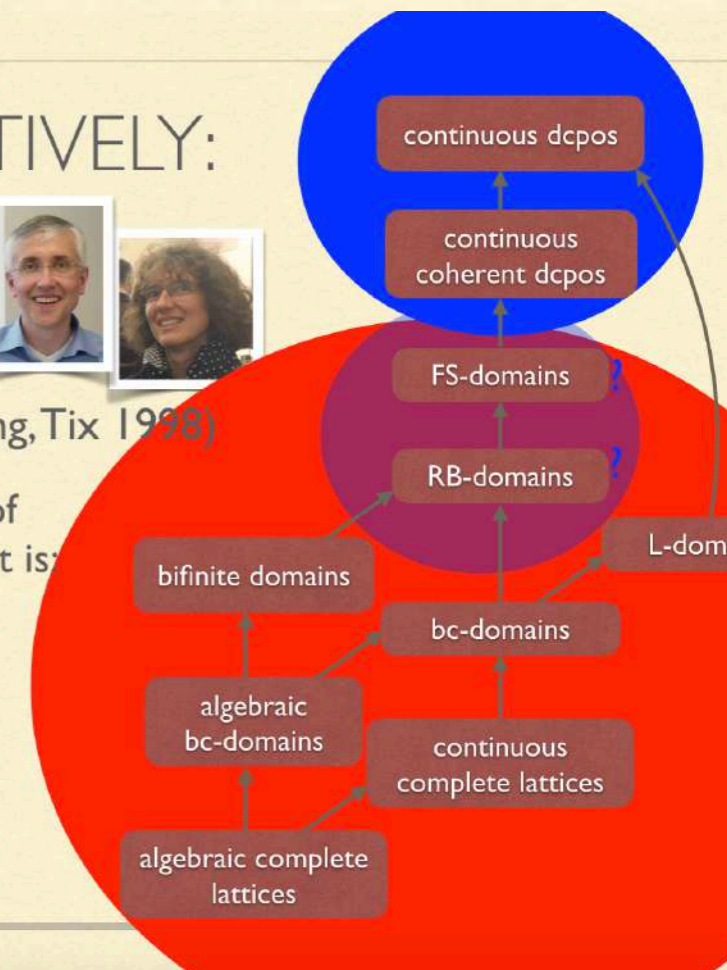
- There is no need to leave domain theory after all
- An easy solution using **call-by-push-value**
- will also handle the mix with **demonic non-determinism**

## MORE POSITIVELY:



(Jung, Tix 1998)

- Look for a category of continuous dcpos that is:
  - **Cartesian-closed**
  - **closed under  $\vee$**



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# TWO KINDS OF TYPES?

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- No such problem with two kinds of types:

$\sigma, \tau, \dots ::= \mathbf{int} \mid \dots \mid \sigma \times \tau \mid \mathbf{V}\tau$

$\underline{\sigma}, \underline{\tau}, \dots ::= \dots \mid \sigma \rightarrow \underline{\tau}$

continuous (coherent) dcpos

bc-domains/continuous lattices

---

# CALL-BY-PUSH-VALUE

- No such problem with two kinds of types:

continuous (coherent) dcpos

$\sigma, \tau, \dots ::= \mathbf{int} \mid \mathbf{unit} \mid \mathbf{U}\underline{\sigma} \mid \sigma \times \tau \mid \mathbf{V}\tau$

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bc-domains/continuous lattices

- This is the type structure of Paul B. Levy's **call-by-push-value** (except for the **V** construction)

## Call-By-Push-Value: A Subsuming Paradigm (extended abstract)

Paul Blain Levy\*

Department of Computer Science, Queen Mary and Westfield College  
LONDON E1 4NS pbl@dcs.qmw.ac.uk

**Abstract.** Call-by-push-value is a new paradigm that subsumes the call-by-name and call-by-value paradigms, in the following sense: both operational and denotational semantics for those paradigms can be seen as arising, via translations that we will provide, from similar semantics for call-by-push-value.

To explain call-by-push-value, we first discuss general operational ideas, especially the distinction between values and computations, using the principle that "a value is, a computation does". Using an example program, we see that the lambda-calculus primitives can be understood as push/pop commands for an operand-stack.

We provide operational and denotational semantics for a range of computational effects and show their agreement. We hence obtain semantics for call-by-name and call-by-value, of which some are familiar, some are new and some were known but previously appeared mysterious.



(Levy 1999)

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(Levy 1999)

---

# U AND F

---

■

$\sigma, \tau, \dots ::= \mathbf{int} \mid \mathbf{unit} \mid$

$\underline{\sigma}, \underline{\tau}, \dots ::= \sigma \rightarrow \underline{\tau}$

$\sigma \times \tau \mid \mathbf{V}\tau$

continuous (coherent) dcpos

bc-domains/continuous lattices

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continuous (coherent) dcpos
  - **U** converts from bc-domains to continuous coherent dcpos  
... semantically the identity:  $\llbracket \mathbf{U}\underline{\sigma} \rrbracket = \llbracket \underline{\sigma} \rrbracket$   
bc-domains/continuous lattices
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# U AND F

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... semantically the identity:  $\llbracket \mathbf{U}\underline{\sigma} \rrbracket = \llbracket \underline{\sigma} \rrbracket$   
bc-domains/continuous lattices
- $M, N, \dots ::= \dots$ 
  - | **force**  $M$      $(\mathbf{U}\underline{\sigma} \rightsquigarrow \underline{\sigma})$
  - | **thunk**  $M$      $(\underline{\sigma} \rightsquigarrow \mathbf{U}\underline{\sigma})$

# U AND F

■

continuous (coherent) dcpos

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| **thunk**  $M$      $(\underline{\sigma} \rightsquigarrow \mathbf{U}\underline{\sigma})$

■  $\llbracket \mathbf{force} M \rrbracket = \llbracket M \rrbracket$

$\llbracket \mathbf{thunk} M \rrbracket = \llbracket M \rrbracket$

■ **force thunk**  $M \rightarrow M$



# U AND F

■

continuous (coherent) dcpos

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... semantically the identity:  $\llbracket \mathbf{U}\underline{\sigma} \rrbracket = \llbracket \underline{\sigma} \rrbracket$

■ **F** converts from continuous coherent dcpos to bc-domains

... Ershov's bounded complete hull would be the canonical choice

■ (but is too intricate for our purposes.)




Theoretical Computer Science 175 (1997) 3–13

The bounded-complete hull of an  $\alpha$ -space

Yu.L. Ershov<sup>\*1</sup>

Research Institute for Informatics and Mathematics, Novosibirsk State University,  
630090 Novosibirsk, Russia



1. Introduction

In the paper [3], the author suggested a general topological approach to domain theory as highly convenient and more general than the established more traditional

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# THE SMYTH POWERDOMAIN

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- $\mathbf{Q}X = \{\text{compact saturated subsets of } X\}$ , reverse inclusion  $\supseteq$
  - **Fact.** For  $X$  continuous coherent dcpo, Ershov's bc-hull of  $X$  is a subspace of  $\mathbf{Q}X$ .
  - $\mathbf{Q}X$  is itself a bc-domain (even a continuous complete lattice), and is much easier to use.
  - Serves as a model of **demonic non-determinism**.
-

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# THE SMYTH POWERDOMAIN

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- $\mathbf{Q}X = \{\text{compact saturated subsets of } X\}$ , reverse inclusion  $\supseteq$  defines a(nother) **monad** on the cat. of cont. coh. dcpos.
  - **Unit:**  $\eta : X \rightarrow \mathbf{Q}X : x \mapsto \uparrow x$  (continuous)
  - **Extension:** for  $f : X \rightarrow L$  where  $L$  continuous complete lattice,  
let  $f^* : \mathbf{Q}X \rightarrow L : Q \mapsto \inf \{f(x) \mid x \in Q\}$ 
    - if  $f$  is continuous then  $f^*$  is continuous
    - $f^* \circ \eta = f$
    - $f^* \circ g^* = (f^* \circ g)^*$
-

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# THE SMYTH<sub>⊥</sub> POWERDOMAIN

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- $\mathbf{Q}_{\perp}X = \mathbf{Q}X$  plus a fresh bottom  $\perp$   
defines a(nother) **monad** on the cat. of cont. coh. dcpos.
  - **Unit:**  $\eta : X \rightarrow \mathbf{Q}_{\perp}X : x \mapsto \hat{\uparrow}x$  (continuous)
  - **Extension:** for  $f : X \rightarrow L$  where  $L$  continuous complete lattice,  
let  $f^* : \mathbf{Q}_{\perp}X \rightarrow L : Q \mapsto \inf \{f(x) \mid x \in Q\}, \perp \mapsto \perp$ 
    - if  $f$  is continuous then  $f^*$  is continuous — and  $f^*$  is **strict** now
    - $f^* \circ \eta = f$
    - $f^* \circ g^* = (f^* \circ g)^*$
-

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# U AND F

---

- $\sigma, \tau, \dots ::= \mathbf{int} \mid \mathbf{unit} \mid \mathbf{U}\underline{\sigma} \mid \sigma \times \tau \mid \mathbf{V}\tau$  continuous (coherent) dcpos  
 $\underline{\sigma}, \underline{\tau}, \dots ::= \mathbf{F}\sigma \mid \sigma \rightarrow \underline{\tau}$  bc-domains/continuous lattices
  - **U** converts from bc-domains to continuous coherent dcpos:  $\llbracket \mathbf{U}\underline{\sigma} \rrbracket = \llbracket \underline{\sigma} \rrbracket$
  - **F** converts from continuous coherent dcpos to bc-domains:  $\llbracket \mathbf{F}\sigma \rrbracket = \mathbf{Q}_\perp \llbracket \sigma \rrbracket$
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- $M, N, \dots ::= \dots$ 
  - choice | **abort**<sub>Fσ</sub>
  - |  $M \oplus N$
  - | **produce**  $M$  ( $\sigma \rightsquigarrow \mathbf{F}\sigma$ )
  - monad |  $M \mathbf{to} x_\sigma \mathbf{in} N$

# U AND F

■

continuous (coherent) dcpos

$\sigma, \tau, \dots ::= \mathbf{int} \mid \mathbf{unit} \mid \mathbf{U}\underline{\sigma} \mid \sigma \times \tau \mid \mathbf{V}\tau$

$\underline{\sigma}, \underline{\tau}, \dots ::= \mathbf{F}\sigma \mid \sigma \rightarrow \underline{\tau}$

bc-domains/continuous lattices

■ **U** converts from bc-domains to continuous coherent dcpos:  $\llbracket \mathbf{U}\underline{\sigma} \rrbracket = \llbracket \underline{\sigma} \rrbracket$

■ **F** converts from continuous coherent dcpos to bc-domains:  $\llbracket \mathbf{F}\sigma \rrbracket = \mathbf{Q}_\perp \llbracket \sigma \rrbracket$

■  $M, N, \dots ::= \dots$

■  $\llbracket \mathbf{abort}_{\mathbf{F}\sigma} \rrbracket = \emptyset$

$\llbracket M \oplus N \rrbracket = \llbracket M \rrbracket \wedge \llbracket N \rrbracket$

$\llbracket \mathbf{produce} M \rrbracket = \eta(\llbracket M \rrbracket)$

$\llbracket M \mathbf{to} x_\sigma \mathbf{in} N \rrbracket =$

$(V \mapsto \llbracket N \rrbracket[x_\sigma := V])^* (\llbracket M \rrbracket)$

choice

| **abort**<sub>**F** $\sigma$</sub>

|  $M \oplus N$

| **produce**  $M$  ( $\sigma \rightsquigarrow \mathbf{F}\sigma$ )

|  $M \mathbf{to} x_\sigma \mathbf{in} N$

monad

# U AND F

■

continuous (coherent) dcpos

$\sigma, \tau, \dots ::= \mathbf{int} \mid \mathbf{unit} \mid \mathbf{U}\underline{\sigma} \mid \sigma \times \tau \mid \mathbf{V}\tau$

$\underline{\sigma}, \underline{\tau}, \dots ::= \mathbf{F}\sigma \mid \sigma \rightarrow \underline{\tau}$

bc-domains/continuous lattices

■ **U** converts from bc-domains to continuous coherent dcpos:  $\llbracket \mathbf{U}\underline{\sigma} \rrbracket = \llbracket \underline{\sigma} \rrbracket$

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■  $M, N, \dots ::= \dots$

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$(V \mapsto \llbracket N \rrbracket[x_\sigma := V])^* (\llbracket M \rrbracket)$

choice

| **abort**<sub>**F** $\sigma$</sub>

|  $M \oplus N$

| **produce**  $M$  ( $\sigma \rightsquigarrow \mathbf{F}\sigma$ )

|  $M \mathbf{to} x_\sigma \mathbf{in} N$

monad

■ **(produce M) to**  $x_\sigma$  **in**  $N \rightarrow N[x_\sigma := M]$  + etc.



- 
- PCF, probabilistic choice, and the trouble with  $\mathbf{V}$
  - Curing the trouble using call-by-push-value
  - Semantics, adequacy, full abstraction
-

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-

# OPERATIONAL SEMANTICS

- A Krivine machine for deterministic operations, working on configurations  $C.M$

$$\begin{array}{ll} C \cdot E[M] \rightarrow CE \cdot M & C[_N] \cdot \lambda x_\sigma.M \rightarrow C \cdot M[x_\sigma := N] \\ C[_ \text{to } x_\sigma \text{ in } N] \cdot \text{produce } M \rightarrow C \cdot N[x_\sigma := M] & C[\text{force } \_] \cdot \text{thunk } M \rightarrow C \cdot M \\ [_] \cdot \text{produce } M \rightarrow [\text{produce } \_] \cdot M & \\ C[\text{pred } \_] \cdot \underline{n} \rightarrow C \cdot \underline{n-1} & C[\text{succ } \_] \cdot \underline{n} \rightarrow C \cdot \underline{n+1} \\ C[\text{ifz } \_ N P] \cdot \underline{0} \rightarrow C \cdot N & C[\text{ifz } \_ N P] \cdot \underline{n} \rightarrow C \cdot P \quad (n \neq 0) \\ C[_; N] \cdot \underline{*} \rightarrow C \cdot N & \\ C[\pi_1 \_] \cdot \langle M, N \rangle \rightarrow C \cdot M & C[\pi_2 \_] \cdot \langle M, N \rangle \rightarrow C \cdot N \\ C[\text{do } x_\sigma \leftarrow \_; N] \cdot \text{ret } M \rightarrow C \cdot N[x_\sigma := M] & [\text{produce } \_] \cdot \text{ret } M \rightarrow [\text{produce ret } \_] \cdot M \\ C \cdot \text{rec } x_\sigma.M \rightarrow C \cdot M[x_\sigma := \text{rec } x_\sigma.M] & \end{array}$$

# OPERATIONAL SEMANTICS

- A Krivine machine for deterministic operations, working on configurations  $C.M$

$$\begin{array}{l}
 C \cdot E[M] \rightarrow CE \cdot M \qquad C[-N] \cdot \lambda x_\sigma.M \rightarrow C \cdot M[x_\sigma := N] \\
 C[- \text{to } x_\sigma \text{ in } N] \cdot \mathbf{produce} M \rightarrow C \cdot N[x_\sigma := M] \quad C[\mathbf{force} \_] \cdot \mathbf{thunk} M \rightarrow C \cdot M \\
 [-] \cdot \mathbf{produce} M \rightarrow [\mathbf{produce} \_] \cdot M \\
 C[\mathbf{pred} \_] \cdot \underline{n} \rightarrow C \cdot \underline{n-1} \qquad C[\mathbf{succ} \_] \cdot \underline{n} \rightarrow C \cdot \underline{n+1} \\
 C[\mathbf{ifz} \_ N P] \cdot \underline{0} \rightarrow C \cdot N \qquad C[\mathbf{ifz} \_ N P] \cdot \underline{n} \rightarrow C \cdot P \quad (n \neq 0) \\
 C[; N] \cdot \underline{*} \rightarrow C \cdot N \\
 C[\pi_1 \_] \cdot \langle M, N \rangle \rightarrow C \cdot M \qquad C[\pi_2 \_] \cdot \langle M, N \rangle \rightarrow C \cdot N \\
 C[\mathbf{do } x_\sigma \leftarrow \_ ; N] \cdot \mathbf{ret} M \rightarrow C \cdot N[x_\sigma := M] \quad [\mathbf{produce} \_] \cdot \mathbf{ret} M \rightarrow [\mathbf{produce ret} \_] \cdot M \\
 C \cdot \mathbf{rec } x_\sigma.M \rightarrow C \cdot M[x_\sigma := \mathbf{rec } x_\sigma.M]
 \end{array}$$

- Prob. must-termination judgments

$$C.M \downarrow a$$

(« whichever way you resolve the demonic non-deterministic choices, the probability that  $C.M$  terminates is  $>a$ . »)

$$\begin{array}{l}
 \frac{}{[\mathbf{produce ret} \_] \cdot \underline{*} \downarrow a} \quad (a \in \mathbb{Q} \cap [0, 1)) \qquad \frac{}{C \cdot M \downarrow 0} \qquad \frac{}{C \cdot \mathbf{abort}_{F_T} \downarrow a} \quad (a \in \mathbb{Q} \cap [0, 1)) \\
 \frac{C' \cdot M' \downarrow a}{C \cdot M \downarrow a} \quad (\text{if } C \cdot M \rightarrow C' \cdot M') \qquad \frac{C \cdot M \downarrow a \quad C \cdot N \downarrow b}{C \cdot M \oplus N \downarrow (a+b)/2} \qquad \frac{C \cdot M \downarrow a \quad C \cdot N \downarrow a}{C \cdot M \otimes N \downarrow a} \\
 \frac{[-] \cdot M \downarrow b \quad C \cdot \underline{*} \downarrow a}{C \cdot \bigcirc_{>b} M \downarrow a} \qquad \frac{C \cdot \mathbf{ifz} M N P \downarrow a}{C \cdot \mathbf{pifz} M N P \downarrow a} \qquad \frac{C \cdot N \downarrow a \quad C \cdot P \downarrow a}{C \cdot \mathbf{pifz} M N P \downarrow a}
 \end{array}$$

# OPERATIONAL SEMANTICS

- A Krivine machine for deterministic operations, working on configurations  $C.M$

$$\begin{array}{l}
 C.E[M] \rightarrow CE.M \qquad C[.N].\lambda x_\sigma.M \rightarrow C.M[x_\sigma := N] \\
 C[. \text{to } x_\sigma \text{ in } N].\text{produce } M \rightarrow C.N[x_\sigma := M] \quad C[\text{force } .].\text{thunk } M \rightarrow C.M \\
 [.].\text{produce } M \rightarrow [\text{produce } .].M \\
 C[\text{pred } .].\underline{n} \rightarrow C.\underline{n-1} \qquad C[\text{succ } .].\underline{n} \rightarrow C.\underline{n+1} \\
 C[\text{ifz } . N P].\underline{0} \rightarrow C.N \qquad C[\text{ifz } . N P].\underline{n} \rightarrow C.P \quad (n \neq 0) \\
 C[.; N].* \rightarrow C.N \\
 C[\pi_1.].\langle M, N \rangle \rightarrow C.M \qquad C[\pi_2.].\langle M, N \rangle \rightarrow C.N \\
 C[\text{do } x_\sigma \leftarrow .; N].\text{ret } M \rightarrow C.N[x_\sigma := M] \quad [\text{produce } .].\text{ret } M \rightarrow [\text{produce ret } .].M \\
 C.\text{rec } x_\sigma.M \rightarrow C.M[x_\sigma := \text{rec } x_\sigma.M]
 \end{array}$$

- Prob. must-termination judgments

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$$\begin{array}{l}
 \frac{}{[\text{produce ret } .].* \downarrow a} \quad (a \in \mathbb{Q} \cap [0, 1)) \qquad \frac{}{C.M \downarrow 0} \qquad \frac{}{C.\text{abort}_{\mathbb{F}_T} \downarrow a} \quad (a \in \mathbb{Q} \cap [0, 1)) \\
 \frac{C'.M' \downarrow a}{C.M \downarrow a} \quad (\text{if } C.M \rightarrow C'.M') \qquad \frac{C.M \downarrow a \quad C.N \downarrow b}{C.M \oplus N \downarrow (a+b)/2} \qquad \frac{C.M \downarrow a \quad C.N \downarrow a}{C.M \otimes N \downarrow a} \\
 \frac{[.].M \downarrow b \quad C.* \downarrow a}{C.\bigcirc_{>b} M \downarrow a} \qquad \frac{C.\text{ifz } M N P \downarrow a}{C.\text{pifz } M N P \downarrow a} \qquad \frac{C.N \downarrow a \quad C.P \downarrow a}{C.\text{pifz } M N P \downarrow a}
 \end{array}$$

- Let  $\text{Pr}(C.M \downarrow) = \sup \{a \mid C.M \downarrow a\}$ ,  $\text{Pr}(M \downarrow) = \text{Pr}([\square].M \downarrow)$

# ADEQUACY

## ■ Prop (adequacy).

For every  $M : \mathbf{FVunit}$ ,

- $\llbracket M \rrbracket = \perp$  and  $\Pr(M \downarrow) = 0$ , or
- $\llbracket M \rrbracket = \emptyset$  and  $\Pr(M \downarrow) = 1$ , or else
- $\Pr(M \downarrow) = \min \{v(\{\top\}) \mid v \in \llbracket M \rrbracket\}$

$$\begin{aligned} \llbracket x_\sigma \rrbracket \rho &= \rho(x_\sigma) \\ \llbracket \lambda x_\sigma. M \rrbracket \rho &= V \in [\sigma] \mapsto \llbracket M \rrbracket (\rho[x_\sigma \mapsto V]) \quad \llbracket MN \rrbracket \rho = \llbracket M \rrbracket \rho(\llbracket N \rrbracket \rho) \\ \llbracket \mathbf{produce} M \rrbracket \rho &= \eta^{\mathcal{Q}}(\llbracket M \rrbracket \rho) \\ \llbracket M \mathbf{to} x_\sigma \mathbf{in} N \rrbracket \rho &= (V \in [\sigma] \mapsto \llbracket N \rrbracket \rho[x_\sigma \mapsto V])^*(\llbracket M \rrbracket \rho) \\ \llbracket \mathbf{thunk} M \rrbracket \rho &= \llbracket M \rrbracket \rho \quad \llbracket \mathbf{force} M \rrbracket \rho = \llbracket M \rrbracket \rho \\ \llbracket * \rrbracket \rho &= \top \quad \llbracket ! \rrbracket \rho = n \\ \llbracket \mathbf{succ} M \rrbracket \rho &= \begin{cases} n + 1 & \text{if } n = \llbracket M \rrbracket \rho \neq \perp \\ \perp & \text{otherwise} \end{cases} \\ \llbracket \mathbf{pred} M \rrbracket \rho &= \begin{cases} n - 1 & \text{if } n = \llbracket M \rrbracket \rho \neq \perp \\ \perp & \text{otherwise} \end{cases} \\ \llbracket \mathbf{ifz} M N P \rrbracket \rho &= \begin{cases} \llbracket N \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho = 0 \\ \llbracket P \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho \neq 0, \perp \\ \perp & \text{if } \llbracket M \rrbracket \rho = \perp \end{cases} \\ \llbracket M; N \rrbracket \rho &= \begin{cases} \llbracket N \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho = \top \\ \perp & \text{otherwise} \end{cases} \\ \llbracket \pi_1 M \rrbracket \rho = m, \llbracket \pi_2 M \rrbracket \rho = n & \text{ where } \llbracket M \rrbracket \rho = (m, n) \\ \llbracket \langle M, N \rangle \rrbracket \rho &= (\llbracket M \rrbracket \rho, \llbracket N \rrbracket \rho) \\ \llbracket \mathbf{ret} M \rrbracket \rho &= \delta_{\llbracket M \rrbracket \rho} \\ \llbracket \mathbf{do} x_\sigma \leftarrow M; N \rrbracket \rho &= (V \in [\sigma] \mapsto \llbracket N \rrbracket \rho[x_\sigma \mapsto V])^\dagger(\llbracket M \rrbracket \rho) \\ \llbracket M \oplus N \rrbracket \rho &= \frac{1}{2}(\llbracket M \rrbracket \rho + \llbracket N \rrbracket \rho) \\ \llbracket M \otimes N \rrbracket \rho &= \llbracket M \rrbracket \rho \wedge \llbracket N \rrbracket \rho \quad \llbracket \mathbf{abort}_{\mathbf{F}\tau} \rrbracket \rho = \emptyset \\ \llbracket \mathbf{rec} x_\sigma. M \rrbracket \rho &= \text{lfp}(V \in [\sigma] \mapsto \llbracket M \rrbracket \rho[x_\sigma \mapsto V]) \end{aligned}$$

# ADEQUACY

- **Prop (adequacy).**

For every  $M : \mathbf{FVunit}$ ,

- $\llbracket M \rrbracket = \perp$  and  $\Pr(M \downarrow) = 0$ , or
- $\llbracket M \rrbracket = \emptyset$  and  $\Pr(M \downarrow) = 1$ , or else
- $\Pr(M \downarrow) = \min \{v(\{\top\}) \mid v \in \llbracket M \rrbracket\}$

- I.e.,  $\Pr(M \downarrow) = h^*(\llbracket M \rrbracket)$

where  $h(v) = v(\{\top\})$

$$\begin{aligned}
 & \llbracket x_\sigma \rrbracket \rho = \rho(x_\sigma) \\
 & \llbracket \lambda x_\sigma. M \rrbracket \rho = V \in [\sigma] \mapsto \llbracket M \rrbracket (\rho[x_\sigma \mapsto V]) \quad \llbracket MN \rrbracket \rho = \llbracket M \rrbracket \rho(\llbracket N \rrbracket \rho) \\
 & \llbracket \mathbf{produce} M \rrbracket \rho = \eta^{\mathcal{Q}}(\llbracket M \rrbracket \rho) \\
 & \llbracket M \mathbf{to} x_\sigma \mathbf{in} N \rrbracket \rho = (V \in [\sigma] \mapsto \llbracket N \rrbracket \rho[x_\sigma \mapsto V])^*(\llbracket M \rrbracket \rho) \\
 & \llbracket \mathbf{thunk} M \rrbracket \rho = \llbracket M \rrbracket \rho \quad \llbracket \mathbf{force} M \rrbracket \rho = \llbracket M \rrbracket \rho \\
 & \llbracket * \rrbracket \rho = \top \quad \llbracket ! \rrbracket \rho = n \\
 & \llbracket \mathbf{succ} M \rrbracket \rho = \begin{cases} n + 1 & \text{if } n = \llbracket M \rrbracket \rho \neq \perp \\ \perp & \text{otherwise} \end{cases} \\
 & \llbracket \mathbf{pred} M \rrbracket \rho = \begin{cases} n - 1 & \text{if } n = \llbracket M \rrbracket \rho \neq \perp \\ \perp & \text{otherwise} \end{cases} \\
 & \llbracket \mathbf{ifz} M N P \rrbracket \rho = \begin{cases} \llbracket N \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho = 0 \\ \llbracket P \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho \neq 0, \perp \\ \perp & \text{if } \llbracket M \rrbracket \rho = \perp \end{cases} \\
 & \llbracket M; N \rrbracket \rho = \begin{cases} \llbracket N \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho = \top \\ \perp & \text{otherwise} \end{cases} \\
 & \llbracket \pi_1 M \rrbracket \rho = m, \llbracket \pi_2 M \rrbracket \rho = n \text{ where } \llbracket M \rrbracket \rho = (m, n) \\
 & \llbracket \langle M, N \rangle \rrbracket \rho = (\llbracket M \rrbracket \rho, \llbracket N \rrbracket \rho) \\
 & \llbracket \mathbf{ret} M \rrbracket \rho = \delta_{\llbracket M \rrbracket \rho} \\
 & \llbracket \mathbf{do} x_\sigma \leftarrow M; N \rrbracket \rho = (V \in [\sigma] \mapsto \llbracket N \rrbracket \rho[x_\sigma \mapsto V])^\dagger(\llbracket M \rrbracket \rho) \\
 & \llbracket M \oplus N \rrbracket \rho = \frac{1}{2}(\llbracket M \rrbracket \rho + \llbracket N \rrbracket \rho) \\
 & \llbracket M \otimes N \rrbracket \rho = \llbracket M \rrbracket \rho \wedge \llbracket N \rrbracket \rho \quad \llbracket \mathbf{abort}_{\mathbf{F}\tau} \rrbracket \rho = \emptyset \\
 & \llbracket \mathbf{rec} x_\sigma. M \rrbracket \rho = \text{lfp}(V \in [\sigma] \mapsto \llbracket M \rrbracket \rho[x_\sigma \mapsto V])
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For every  $M : \mathbf{FVunit}$ ,
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  - $\Pr(M \downarrow) = \min \{v(\{\top\}) \mid v \in \llbracket M \rrbracket\}$
- I.e.,  $\Pr(M \downarrow) = h^*(\llbracket M \rrbracket)$   
where  $h(v) = v(\{\top\})$
- Proof: by suitable logical relations.

$$\begin{aligned}
 & \llbracket x_\sigma \rrbracket \rho = \rho(x_\sigma) \\
 & \llbracket \lambda x_\sigma. M \rrbracket \rho = V \in [\sigma] \mapsto \llbracket M \rrbracket (\rho[x_\sigma \mapsto V]) \quad \llbracket MN \rrbracket \rho = \llbracket M \rrbracket \rho(\llbracket N \rrbracket \rho) \\
 & \llbracket \mathbf{produce} M \rrbracket \rho = \eta^{\mathcal{Q}}(\llbracket M \rrbracket \rho) \\
 & \llbracket M \mathbf{to} x_\sigma \mathbf{in} N \rrbracket \rho = (V \in [\sigma] \mapsto \llbracket N \rrbracket \rho[x_\sigma \mapsto V])^*(\llbracket M \rrbracket \rho) \\
 & \llbracket \mathbf{thunk} M \rrbracket \rho = \llbracket M \rrbracket \rho \quad \llbracket \mathbf{force} M \rrbracket \rho = \llbracket M \rrbracket \rho \\
 & \llbracket * \rrbracket \rho = \top \quad \llbracket ! \rrbracket \rho = n \\
 & \llbracket \mathbf{succ} M \rrbracket \rho = \begin{cases} n + 1 & \text{if } n = \llbracket M \rrbracket \rho \neq \perp \\ \perp & \text{otherwise} \end{cases} \\
 & \llbracket \mathbf{pred} M \rrbracket \rho = \begin{cases} n - 1 & \text{if } n = \llbracket M \rrbracket \rho \neq \perp \\ \perp & \text{otherwise} \end{cases} \\
 & \llbracket \mathbf{ifz} M N P \rrbracket \rho = \begin{cases} \llbracket N \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho = 0 \\ \llbracket P \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho \neq 0, \perp \\ \perp & \text{if } \llbracket M \rrbracket \rho = \perp \end{cases} \\
 & \llbracket M; N \rrbracket \rho = \begin{cases} \llbracket N \rrbracket \rho & \text{if } \llbracket M \rrbracket \rho = \top \\ \perp & \text{otherwise} \end{cases} \\
 & \llbracket \pi_1 M \rrbracket \rho = m, \llbracket \pi_2 M \rrbracket \rho = n \text{ where } \llbracket M \rrbracket \rho = (m, n) \\
 & \llbracket \langle M, N \rangle \rrbracket \rho = (\llbracket M \rrbracket \rho, \llbracket N \rrbracket \rho) \\
 & \llbracket \mathbf{ret} M \rrbracket \rho = \delta_{\llbracket M \rrbracket \rho} \\
 & \llbracket \mathbf{do} x_\sigma \leftarrow M; N \rrbracket \rho = (V \in [\sigma] \mapsto \llbracket N \rrbracket \rho[x_\sigma \mapsto V])^\dagger(\llbracket M \rrbracket \rho) \\
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 & \llbracket M \otimes N \rrbracket \rho = \llbracket M \rrbracket \rho \wedge \llbracket N \rrbracket \rho \quad \llbracket \mathbf{abort}_{\mathbf{F}\tau} \rrbracket \rho = \emptyset \\
 & \llbracket \mathbf{rec} x_\sigma. M \rrbracket \rho = \text{lfp}(V \in [\sigma] \mapsto \llbracket M \rrbracket \rho[x_\sigma \mapsto V])
 \end{aligned}$$



# NOTE

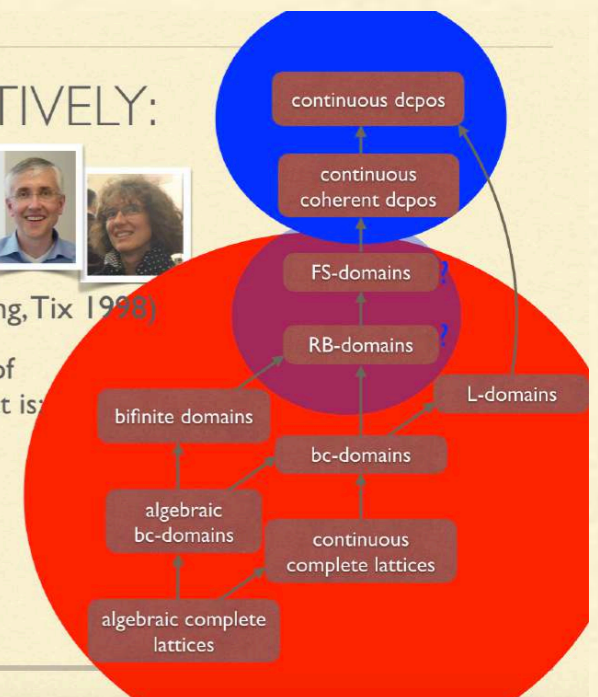
- None of that yet requires CCCs of **continuous** (or algebraic) domains

MORE POSITIVELY:



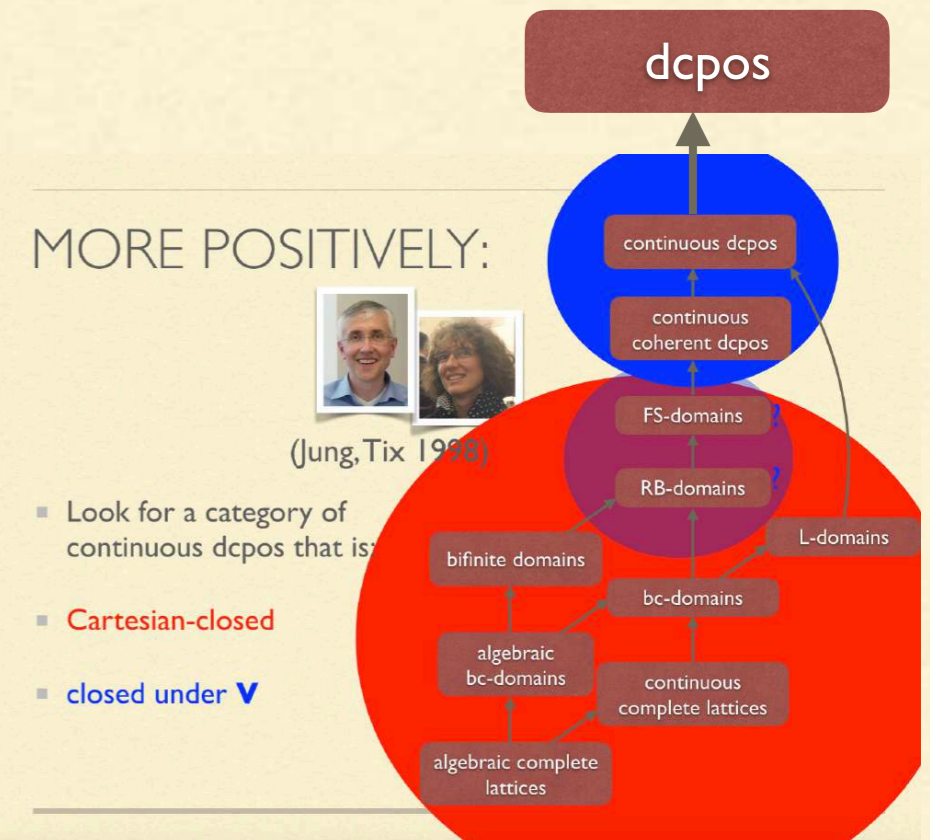
(Jung, Tix 1998)

- Look for a category of continuous dcpos that is:
- Cartesian-closed**
- closed under  $\vee$**



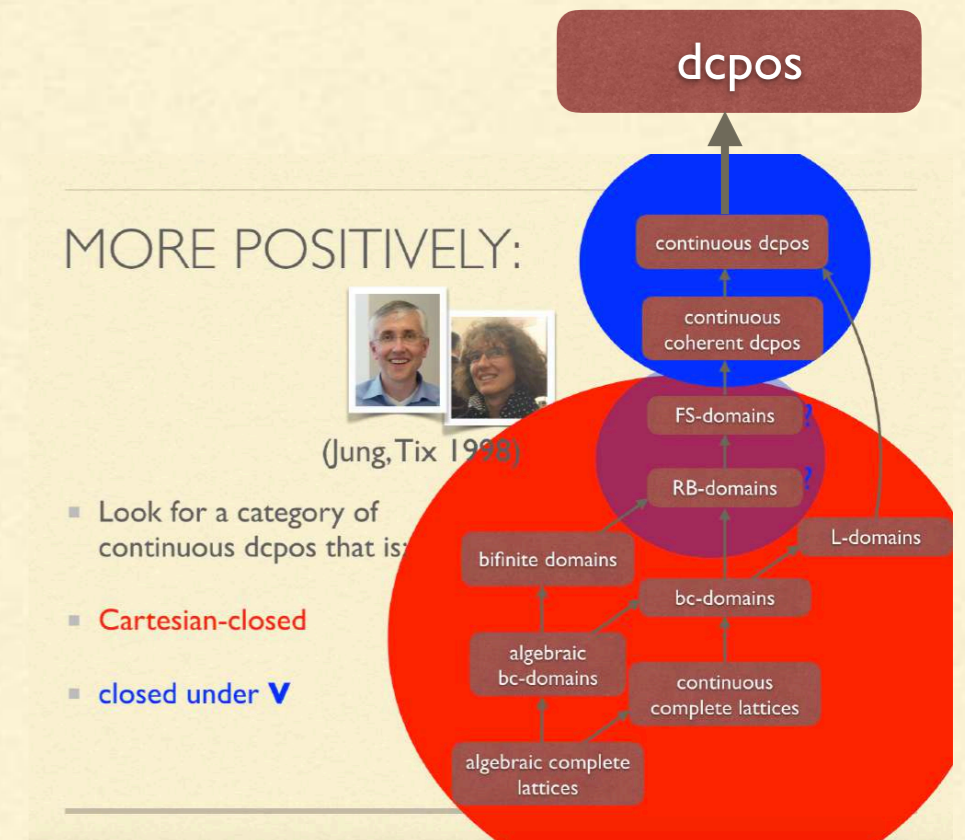
# NOTE

- None of that yet requires CCCs of **continuous** (or algebraic) domains
- Soundness/adequacy works even for non-call-by-push-value probabilistic languages, working in the CCC **Dcpo**



# NOTE

- None of that yet requires CCCs of **continuous** (or algebraic) domains
- Soundness/adequacy works even for non-call-by-push-value probabilistic languages, working in the CCC **Dcpo**
- Continuity is only needed for more advanced applications:
  - full abstraction (next)
  - commutativity of the  $\mathbf{V}$  monad (Fubini) at higher types



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# THE CONTEXTUAL PREORDER

---

- Let  $M \leq N$  iff for every context  $C$  of output type **FVunit**,  
 $\Pr(C . M \downarrow) \leq \Pr(C . N \downarrow)$

---

# THE CONTEXTUAL PREORDER

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- Let  $M \leq N$  iff for every context  $C$  of output type **FVunit**,  
$$\Pr(C . M \downarrow) \leq \Pr(C . N \downarrow)$$
- $M \leq N$  iff for every context  $C$  of output type **FVunit**,  
$$h^*(\llbracket C[M] \rrbracket) \leq h^*(\llbracket C[N] \rrbracket) \quad (\text{adequacy})$$

---

# THE CONTEXTUAL PREORDER

---

- Let  $M \leq N$  iff for every context  $C$  of output type **FVunit**,  
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  - **Corollary.** If  $\llbracket M \rrbracket \leq \llbracket N \rrbracket$  then  $M \leq N$ .
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$$h^*([C[M]]) \leq h^*([C[N]])$$
 (adequacy)
  - **Corollary.** If  $[M] \leq [N]$  then  $M \leq N$ .
  - Proof.  $[C[M]] = [C]([M]) \leq [C]([N]) = [C[N]]$   
since  $[C]$  ( $= [\lambda x . C[x]]$ ) is Scott-continuous hence monotonic.  
Then apply  $h^*$ , which is monotonic as well.  $\square$
-

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# THE APPLICATIVE PREORDER

---

- Let  $M \leq N$  iff for every context  $C$  of output type **FVunit**,  
 $\Pr(C . M \downarrow) \leq \Pr(C . N \downarrow)$
  - Let  $M \leq^{\text{app}} N$  iff for every term  $P : \tau \rightarrow \mathbf{FVunit}$ ,  
 $\Pr(PM \downarrow) \leq \Pr(PN \downarrow)$
-



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  - **Proposition** (« Milner's context lemma » in PCF):  
$$M \leq N \text{ iff } M \leq^{\text{app}} N.$$
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  - **Proposition** (« Milner's context lemma » in PCF):  
$$M \leq N \text{ iff } M \leq^{\text{app}} N.$$
  - Proof: based on an idea of A. Jung (Streicher 06), reusing our previous logical relation.
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# FULL ABSTRACTION?

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- **Conjecture (full abstraction):**  $\llbracket M \rrbracket \leq \llbracket N \rrbracket$  iff  $M \leq N$ .

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  - **Wrong.** (As in (Plotkin 77).) Using another logical relation, for every  $P : \mathbf{int} \rightarrow \mathbf{int} \rightarrow \mathbf{Fint}$ , if  $\llbracket P \rrbracket(\perp)(0) = \llbracket P \rrbracket(0)(\perp) = \{0\}$   
then  $\llbracket P \rrbracket(\perp)(\perp) = \{0\}$
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  - Hence with  $M = \lambda P . P\Omega 0 == 0 \ \&\& \ P 0 \Omega == 0$   
 $N = \lambda P . MP \ \&\& \ P\Omega\Omega == 0$  (and some syntactic sugar)  
we have  $M \leq N$ .
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 $N = \lambda P . MP \ \&\& \ P\Omega\Omega == 0$  (and some syntactic sugar)  
we have  $M \leq N$ .
  - But  $\llbracket M \rrbracket \not\leq \llbracket N \rrbracket$  since  $\llbracket M \rrbracket(\text{por}) = \top$ ,  $\llbracket N \rrbracket(\text{por}) = \perp$ .
-

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# FULL ABSTRACTION?

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- Add parallel if **pifz**:

$\llbracket \mathbf{pifz} \ M \ N \ P \rrbracket = \llbracket N \rrbracket$  if  $\llbracket M \rrbracket = 0$

$\llbracket P \rrbracket$  if  $\llbracket M \rrbracket \neq 0, \perp$

$\llbracket N \rrbracket \wedge \llbracket P \rrbracket$  (not  $\perp!$ ) if  $\llbracket M \rrbracket = \perp$

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  - **Conjecture (full abstraction):**  $\llbracket M \rrbracket \leq \llbracket N \rrbracket$  iff  $M \leq N$ .
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  - **Conjecture (full abstraction):**  $\llbracket M \rrbracket \leq \llbracket N \rrbracket$  iff  $M \leq N$ .
  - **Still wrong.** As in (GL 15), missing statistical termination testers.
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# STATISTICAL TERMINATION TESTERS

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■ Let  $M = \lambda P . P(\Omega \oplus \mathbf{ret}^*)$

$N = \lambda P . P(\Omega) \oplus \mathbf{ret}^*$

(modulo some missing **force**, **produce**, etc.)

Then  $M \leq N$ , even with **pifz**

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# STATISTICAL TERMINATION TESTERS

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- Let  $M = \lambda P . P(\Omega \oplus \mathbf{ret}^*)$   
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Then  $M \leq N$ , even with **pifz**
  - But  $\llbracket M \rrbracket \not\leq \llbracket N \rrbracket$  since  $\llbracket M \rrbracket(\llbracket >b \rrbracket) = \uparrow \delta_{\top}$ ,  $\llbracket N \rrbracket(\llbracket >b \rrbracket) = \perp$  for all  $b < 1/2$ ,  
where  $\llbracket >b \rrbracket : \llbracket \mathbf{Vunit} \rrbracket \rightarrow \llbracket \mathbf{FVunit} \rrbracket$   
maps every  $v$  to ‘termination’ ( $\uparrow \delta_{\top}$ ) if  $v(\{\top\}) > b$ ,  
to  $\perp$  otherwise.
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maps every  $v$  to ‘termination’ ( $\uparrow \delta_{\top}$ ) if  $v(\{\top\}) > b$ ,  
to  $\perp$  otherwise.
  - $\llbracket >b \rrbracket$  tests whether the prob. that its argument terminates is  $> b$ .
-

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# FULL ABSTRACTION

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- Add **pifz** +  $\bigcirc_{>b}$  (with the semantics of  $[>b]$ ,  $0 < b < 1$  dyadic)

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- Add **pifz** +  $\bigcirc_{>b}$  (with the semantics of  $[>b]$ ,  $0 < b < 1$  dyadic)
  - **Theorem (full abstraction):** with **pifz** and  $\bigcirc_{>b}$ ,  
 $\llbracket M \rrbracket \leq \llbracket N \rrbracket$  iff  $M \leq N$ .
  - And now a glimpse of the argument...
-

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# FULL ABSTRACTION: PROOF

---

- We assume  $\llbracket M \rrbracket \not\leq \llbracket N \rrbracket$ , and we wish to prove not  $(M \leq N)$ .



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  - If  $U$  is **definable** by a term  $P$   
(i.e.,  $\llbracket P \rrbracket$  maps each  $x \in U$  to  $\uparrow\delta_{\top}$  and each  $x \notin U$  to  $\perp$ )  
then  $\llbracket PM \rrbracket = \uparrow\delta_{\top}$ ,  $\llbracket PN \rrbracket = \perp$ , so not  $(M \leq^{\text{app}} N)$ .  
Conclude by Milner's context lemma.
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then  $\llbracket PM \rrbracket = \uparrow\delta_{\top}$ ,  $\llbracket PN \rrbracket = \perp$ , so not  $(M \leq^{\text{app}} N)$ .  
Conclude by Milner's context lemma.
  - Challenge: show that each  $\llbracket \tau \rrbracket$  has a subbase of definable opens.
-

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# PROBABILISTIC TYPES

---

- $[[\mathbf{V}\sigma]]$ : subbasic opens  $[U > b]$   
where  $U$  is a basic open of  $[[\sigma]]$ ,  $b$  dyadic in  $(0, 1)$

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  - *test*  $v \in [U>b]$ : iff  $v(U) > b$ , implemented through  
' $\bigcirc_{>b} (\mathbf{do} x_\sigma \leftarrow v; \langle \text{test } x_\sigma \in U \rangle)$ '
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 $\text{‘}\bigcirc_{>b} (\mathbf{do} \ x_\sigma \leftarrow v; \langle \text{test } x_\sigma \in U \rangle)$
  - Note:  $[[\mathbf{V}\sigma]]$  also has a basis of  
 $\sum_x a_x \delta_x$ ,  $a_x$  dyadic, each  $x$  from a basis of  $[[\sigma]]$   
implementable using **ret** and  $\oplus$
-

---

# F TYPES

---

- $[[\mathbf{F}\sigma]]$ : subbasic opens  $\square U$   
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  - $\text{test } Q \in \square U$ : iff  $Q \subseteq U$ , implemented through  
' $Q$  **to**  $x_\sigma$  **in**  $\langle \text{test } x_\sigma \in U \rangle$ '
-

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  - *test*  $Q \in \square U$ : iff  $Q \subseteq U$ , implemented through  
'**Q to**  $x_\sigma$  **in**  $\langle \text{test } x_\sigma \in U \rangle$ '
  - Note:  $[[\mathbf{F}\sigma]]$  also has a basis of  $\uparrow \{x_1, \dots, x_n\}$ ,  
(each  $x_i$  from a basis of  $[[\sigma]]$ ), plus  $\perp$ ,  
implementable using **produce**, **abort**, and  $\bigwedge$
-

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# FUNCTION TYPES (1/2)

---

- $[\sigma \rightarrow \tau]$ : subbasic opens  $[x \mapsto V]$ ,  
where  $x$  is from some basis of  $[\sigma]$ ,  
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  - *test*  $f$  in  $[x \mapsto V]$ : iff  $f(x) \in V$ , implemented straightforwardly
  - Note we need to also define a **basis** of each type  $[\sigma]$  now.  
We have them for **V** and **F** types, and the difficult case is for  $\rightarrow$ .
-

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# FUNCTION TYPES (2/2)

---

- Basis for  $[[\sigma \rightarrow \tau]]$ : step functions  $\bigvee_{1 \leq i \leq n} U_i \searrow y_i$   
mapping each  $x$  to  $\bigvee \{y_i \mid x \in U_i\} \dots$   
but that sup is hard to implement — we only have infs.
-



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but that sup is hard to implement — we only have infs.
  - Trick: for each subset  $I$  of  $\{1, \dots, n\}$ ,  
let  $U_I =$  intersection of  $U_i, i$  in  $I$ ,  
 $y_I =$  sup of  $y_i, i$  in  $I$ .  
Then  $\bigvee_{1 \leq i \leq n} U_i \searrow y_i (x) = \inf \{y_I \mid I \supseteq I_x\}$  where  $I_x = \{i \mid x \in U_i\}$
-

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Then  $\forall 1 \leq i \leq n \ U_i \mapsto y_i (x) = \inf \{y_I \mid I \supseteq I_x\}$  where  $I_x = \{i \mid x \in U_i\}$
  - Additional difficulties (need for **pifz** notably)... omitted. Done!  $\square$
-

# SUMMARY

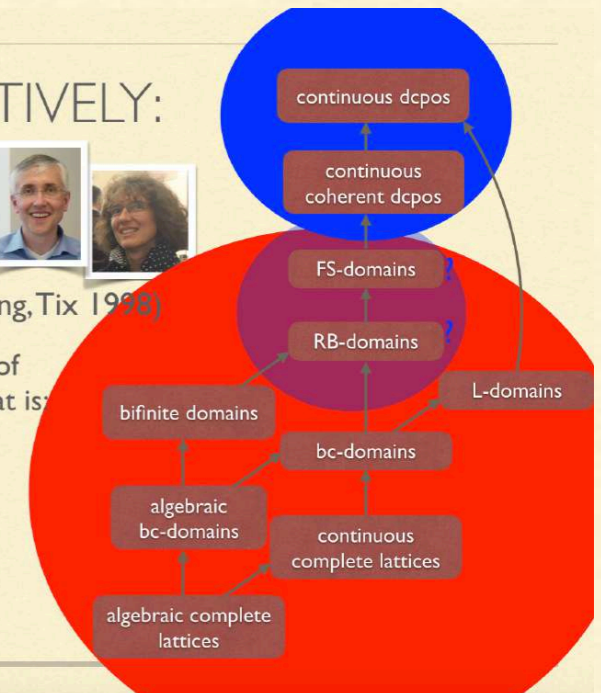
- Circumventing the trouble with  $\mathbf{V}$  by using two classes of types, as provided by call-by-push-value
- We obtain (inequational) full abstraction with prob. choice + demonic non-determinism
- Questions?

## MORE POSITIVELY:



(Jung, Tix 1998)

- Look for a category of continuous dcpos that is
- Cartesian-closed
- closed under  $\mathbf{V}$



## CALL-BY-PUSH-VALUE

- No such problem with two kinds of types:  
 $\sigma, \tau, \dots ::= \mathbf{int} \mid \mathbf{unit} \mid \mathbf{U}\sigma \mid \sigma \times \tau \mid \mathbf{V}\tau$  value types  
 $\alpha, \mathbf{I}, \dots ::= \mathbf{F}\sigma \mid \sigma \rightarrow \mathbf{I}$  computation types
- This is the type structure of Paul B. Levy's call-by-push-value

### Call-By-Push-Value: A Subsuming Paradigm (extended abstract)

Paul Blain Levy\*

Department of Computer Science, Queen Mary and Westfield College  
LONDON E1 4NS paul@cs.qmw.ac.uk

**Abstract.** Call-by-push-value is a new paradigm that subsumes the call-by-name and call-by-value paradigms, in the following sense: both operational and denotational semantics for these paradigms can be seen as arising via translations that we will provide, from similar semantics for call-by-push-value. To explain call-by-push-value, we first discuss general operational ideas, especially the distinction between values and computations, using the principle that 'a value is, a computation done'. Using an example program, we see that the lambda-calculus paradigm can be understood as push/pop constructs for an operand-stack. We provide operational and denotational semantics for a range of computational effects and show their agreement. We know of no semantics for call-by-name and call-by-value, of which some are familiar, some are new and some were known but previously appeared anonymous.



(Levy 1999)